



Hamilton Institute



**Maynooth
University**
National University
of Ireland Maynooth

An efficient algorithm to compute the minimum free energy of interacting nucleic acid strands

Ahmed Shalaby, Damien Woods

Final year PhD



Taighde Éireann
Research Ireland

European
Innovation
Council



Funded by
the European Union







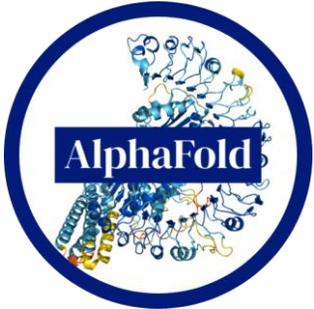
RNA/DNA folding problem



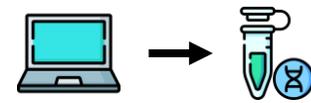
RNA/DNA folding problem



Aptamers: Movie by WuXi AppTec



RNA/DNA folding problem



DNA Computing



Aptamers: Movie by WuXi AppTec



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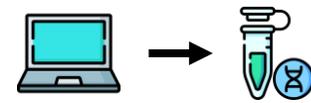


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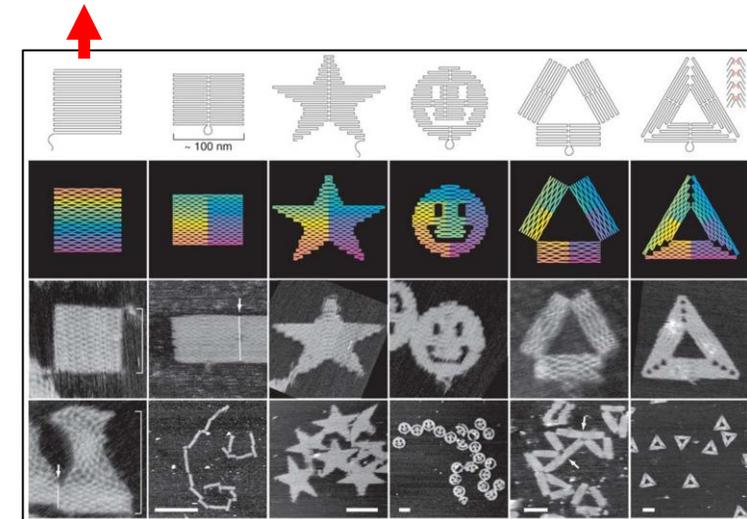
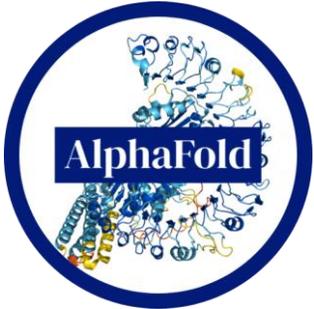


DNA Computing



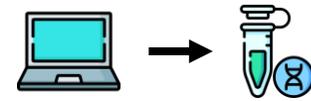
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Rothemund 2006

RNA/DNA folding problem

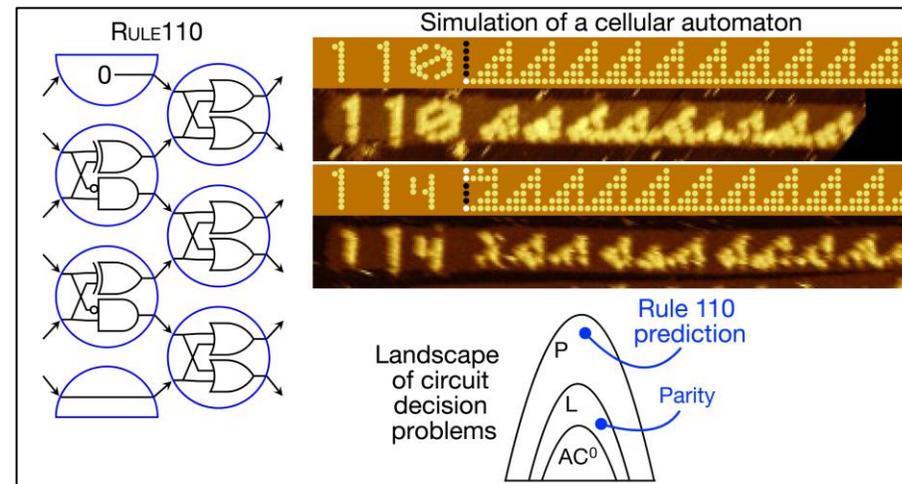
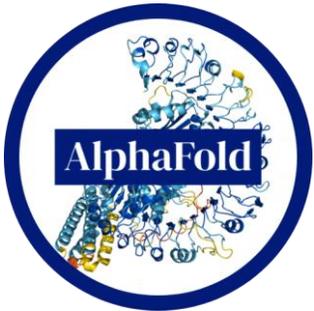


DNA Computing

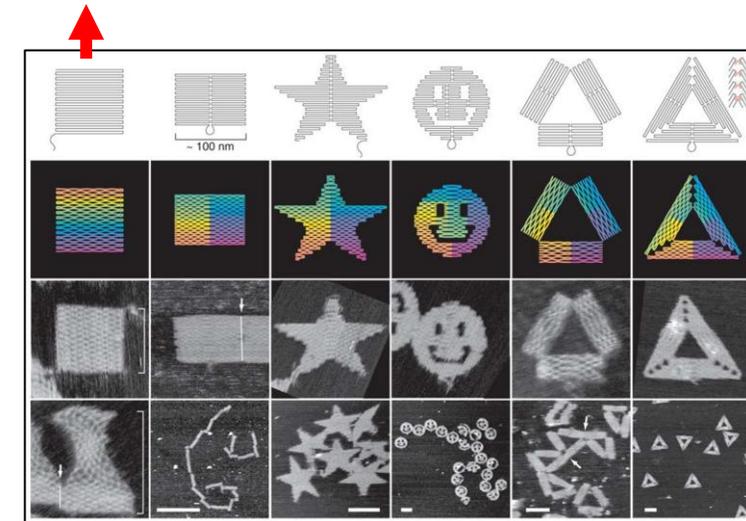


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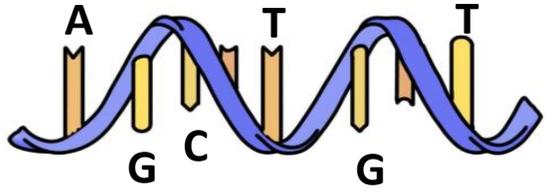


Doty, Woods et al. 2017

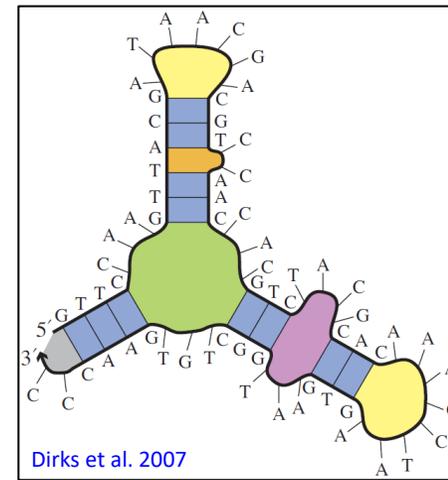
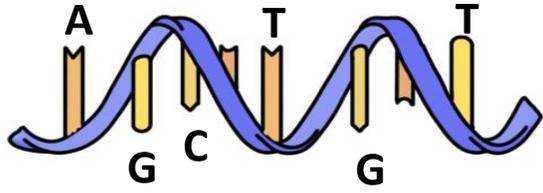


Rothemund 2006

RNA/DNA secondary structure



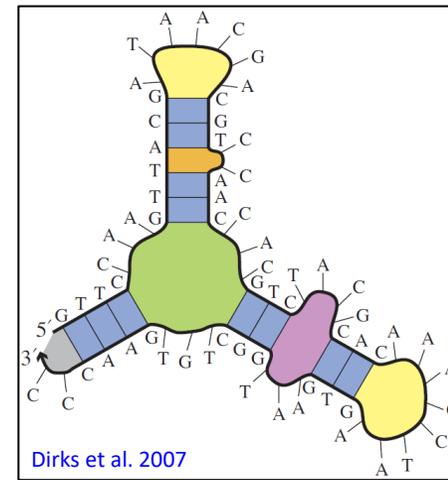
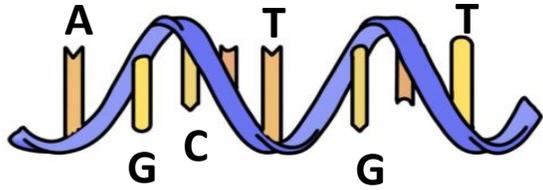
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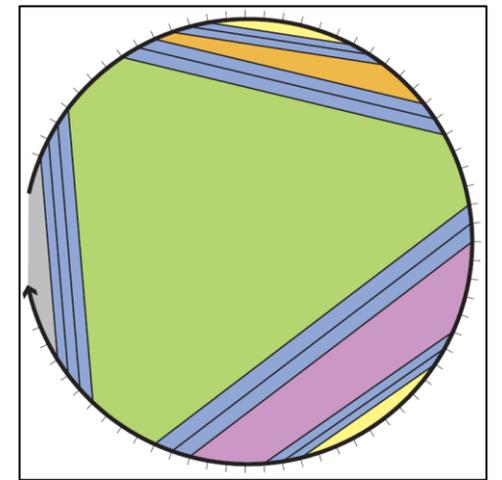
Dirks et al. 2007

Secondary structure

RNA/DNA secondary structure

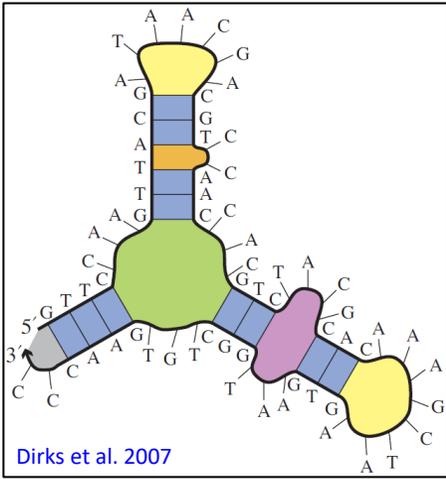
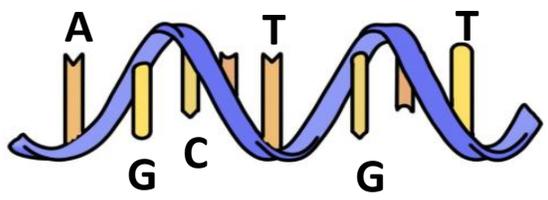


Secondary structure



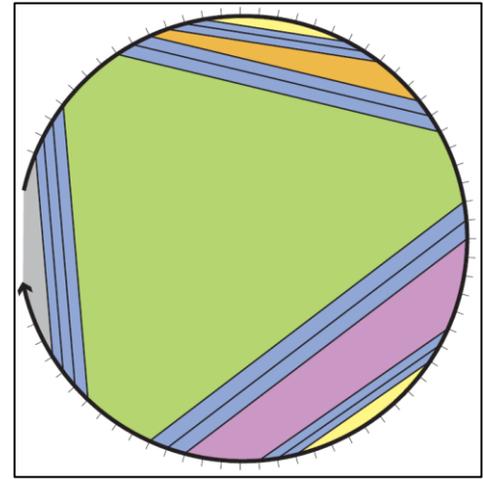
Polymer graph representation

RNA/DNA secondary structure



Dirks et al. 2007

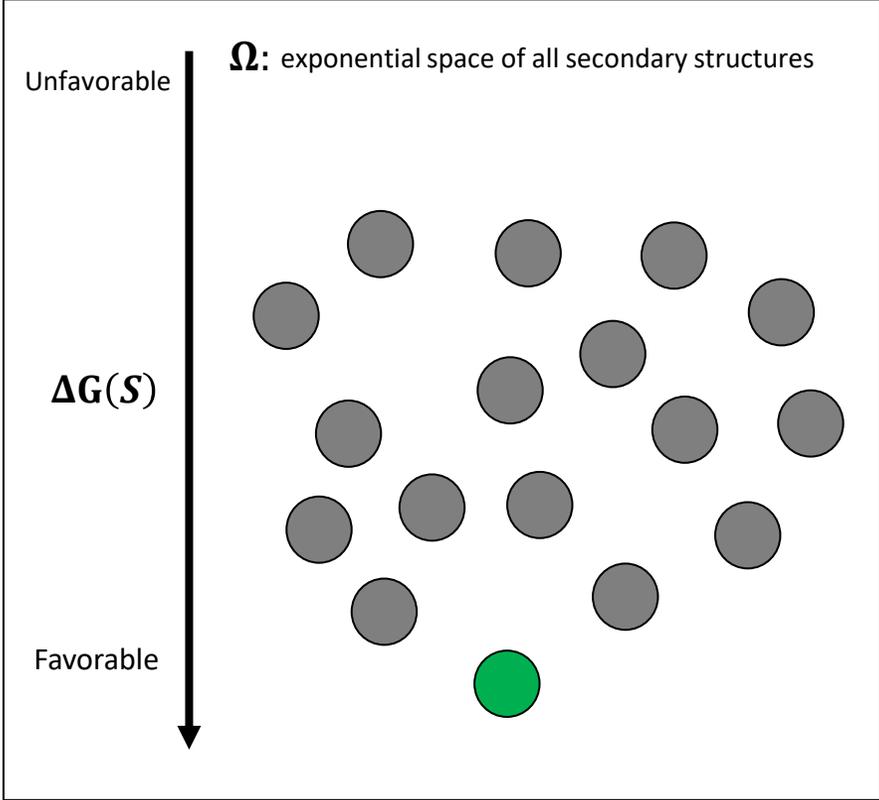
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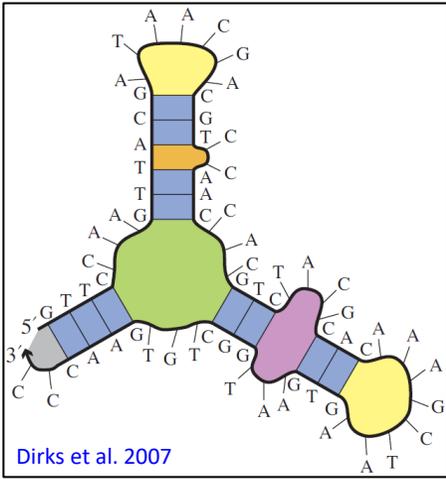
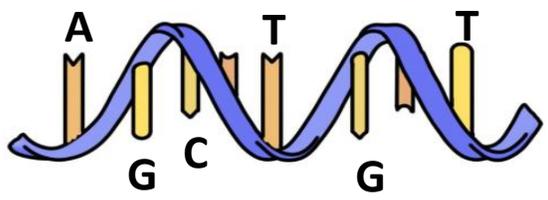
Polymer graph representation

$$\Delta G(S)$$

Energy model

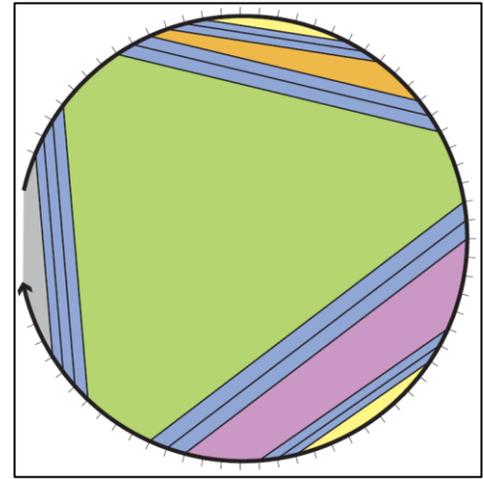


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Dirks et al. 2007

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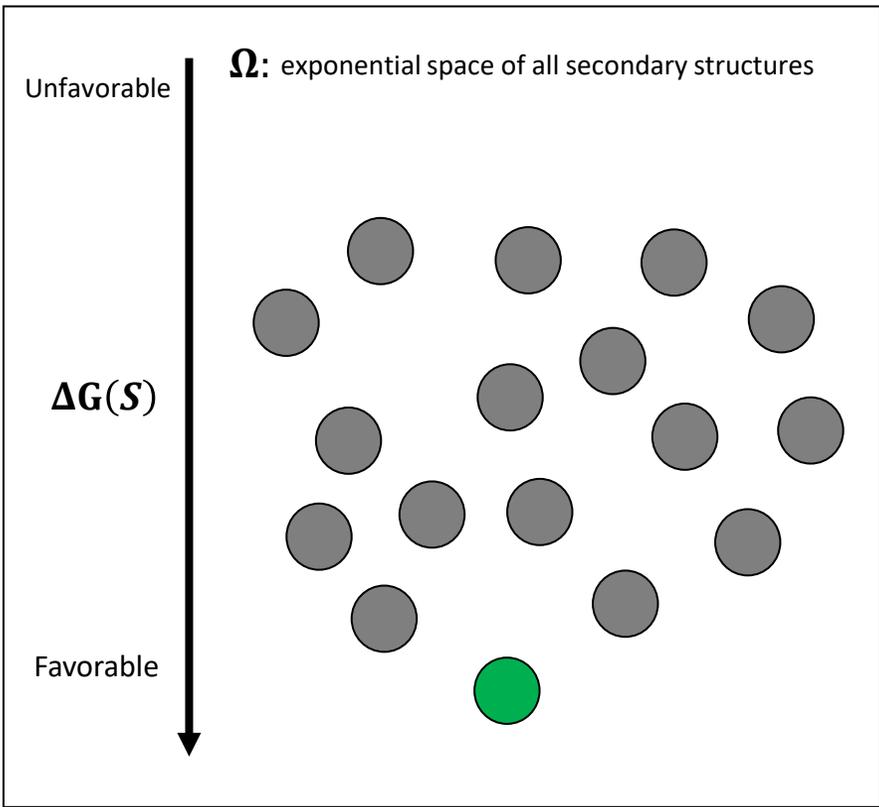


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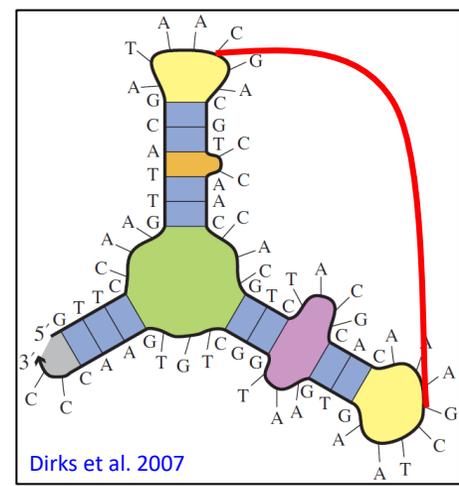
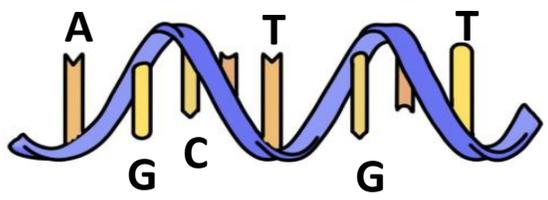
$$\Delta G(S)$$

Energy model

$$\text{MFE} = \min_{S \in \Omega} \Delta G(S)$$

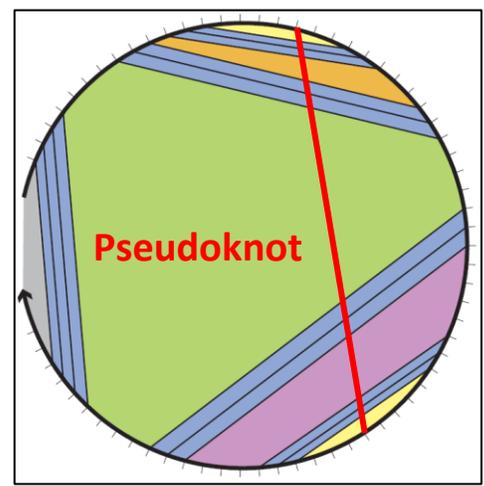


RNA/DNA secondary structure



Dirks et al. 2007

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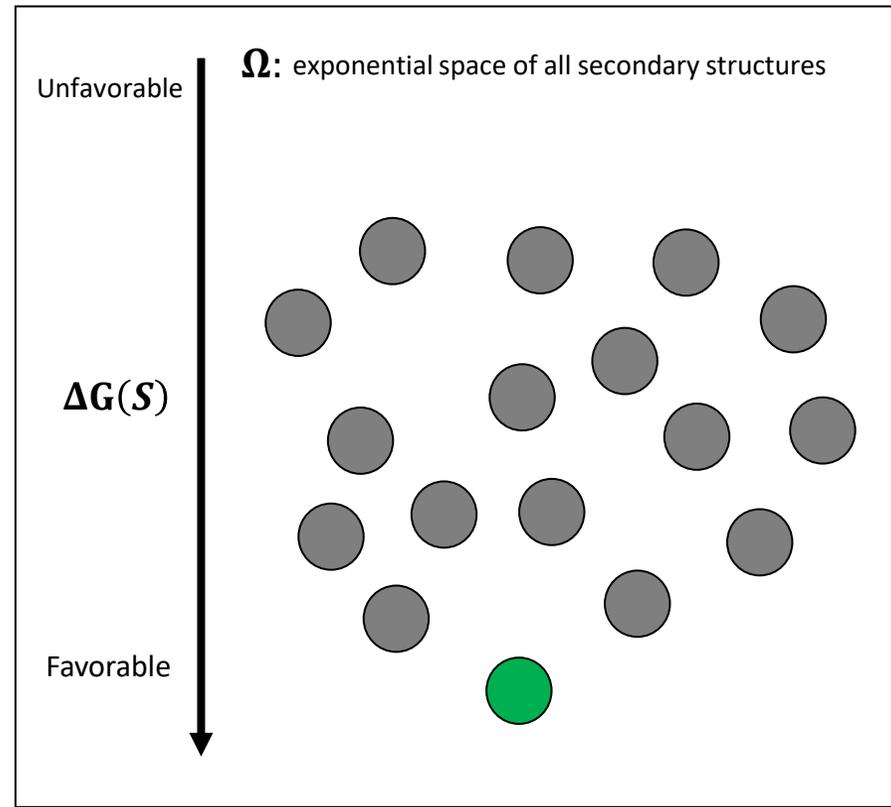
Polymer graph representation

NP – Complete

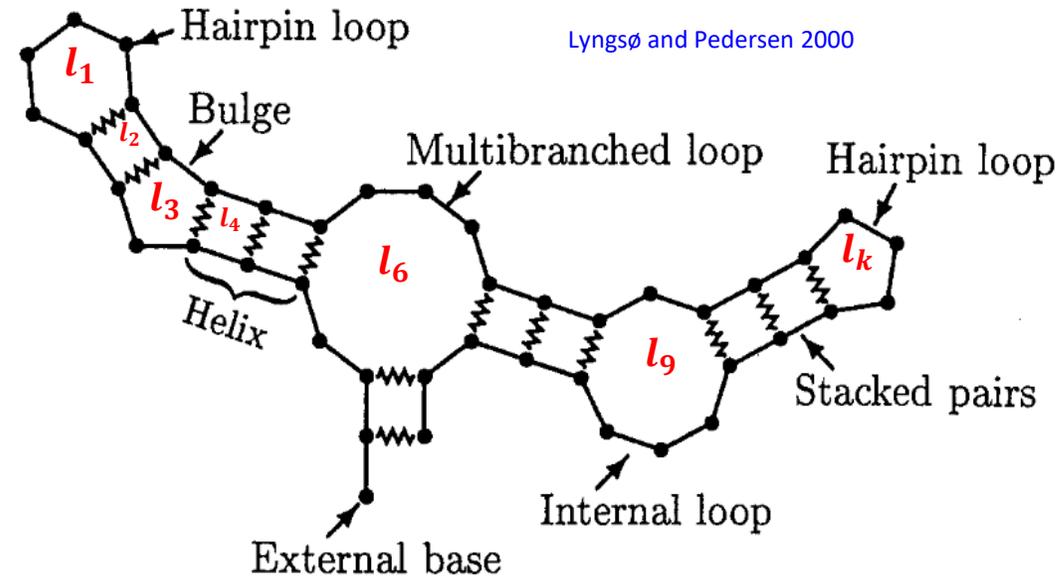
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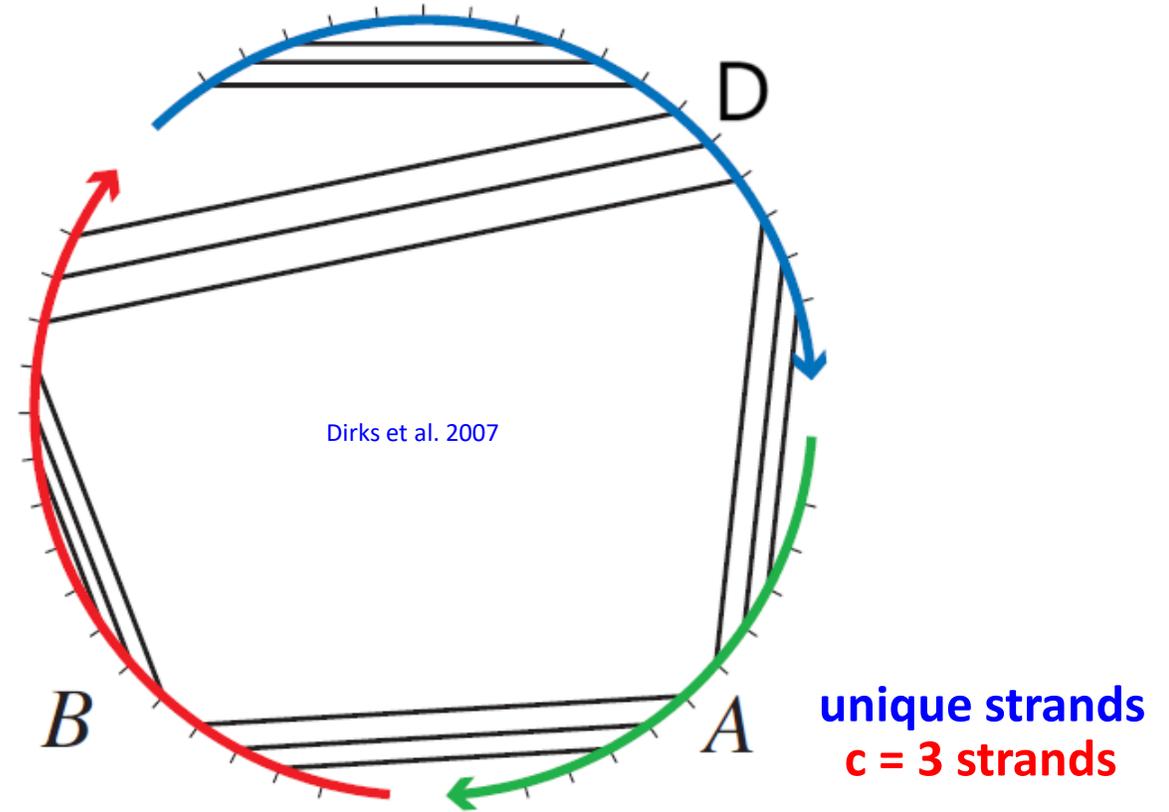
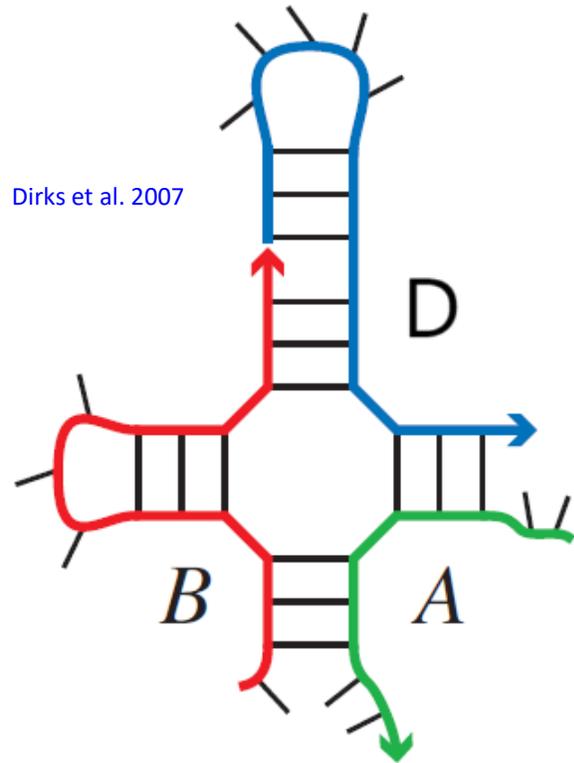
Energy model: Nearest neighbour model



$$\Delta G(S) = \Delta G(l_1) + \Delta G(l_2) + \dots + \Delta G(l_k)$$

$$\Delta G(S) = \sum_{l \in S} \Delta G(l)$$

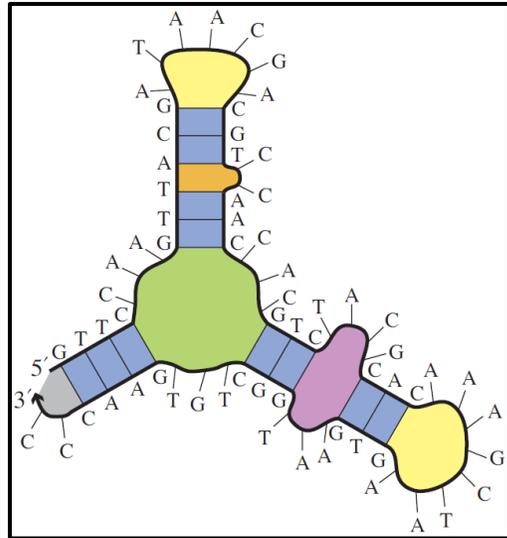
Energy model: Nearest neighbour model



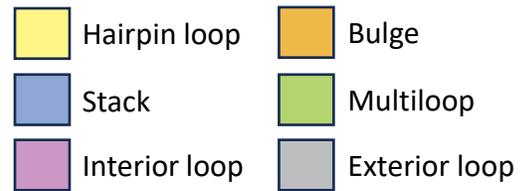
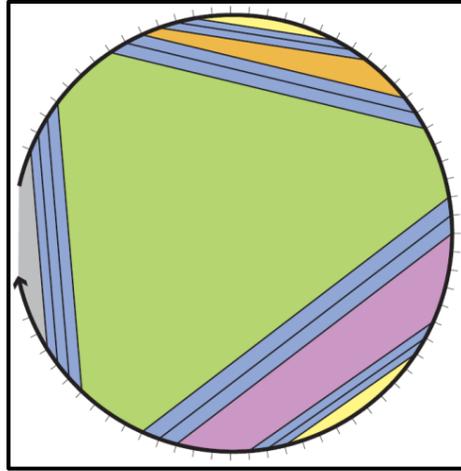
$$\Delta G(S) = \sum_{l \in S} \Delta G(l) + (c - 1) \Delta G^{\text{assoc}}$$

The Nearest Neighbour model for RNA/DNA

Single stranded system



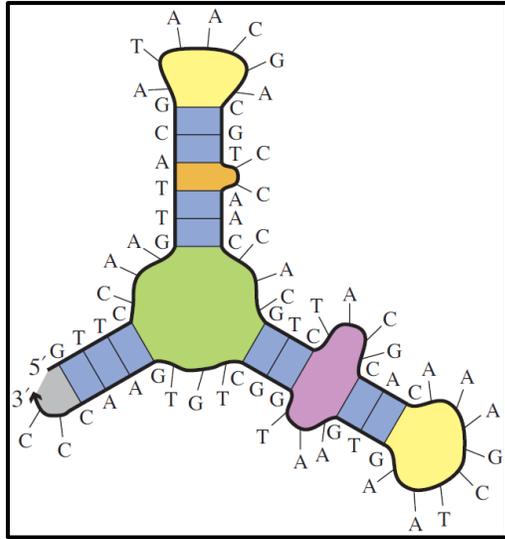
Dirks et al. 2007



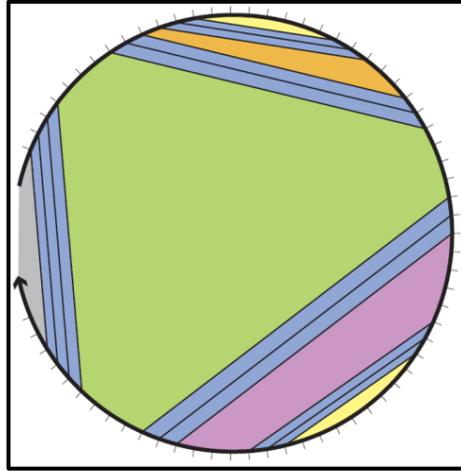
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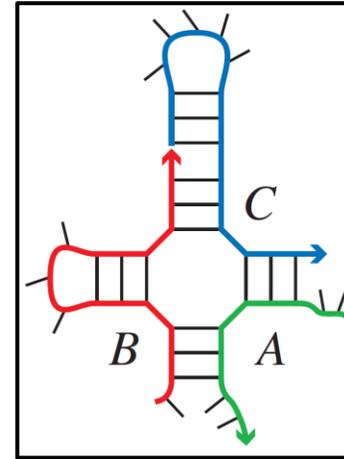
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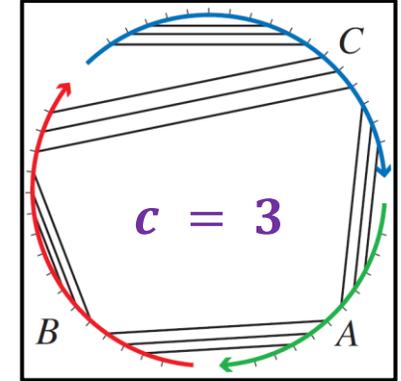
- | | |
|---------------|---------------|
| Hairpin loop | Bulge |
| Stack | Multiloop |
| Interior loop | Exterior loop |

$$\Delta G(S) = \sum_{l \in S} \Delta G(l)$$

Multi-stranded system of c strands



Dirks et al. 2007



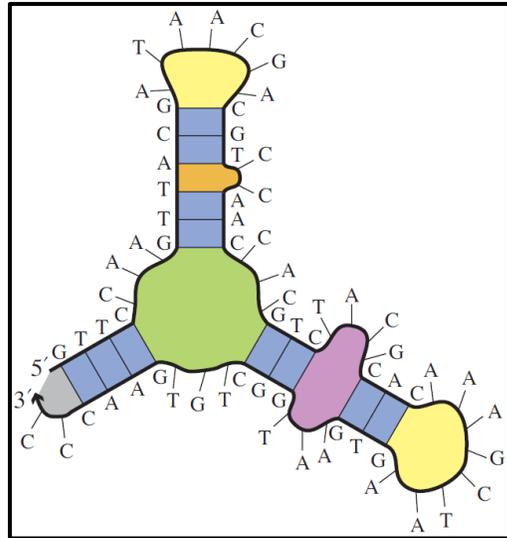
unique strands

$$\Delta G(S) = \sum_l \Delta G(l) + \underbrace{(c - 1) \Delta G^{\text{assoc}}}_{\text{Initiation penalty}}$$

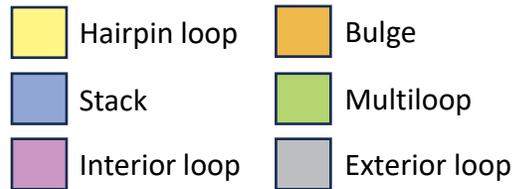
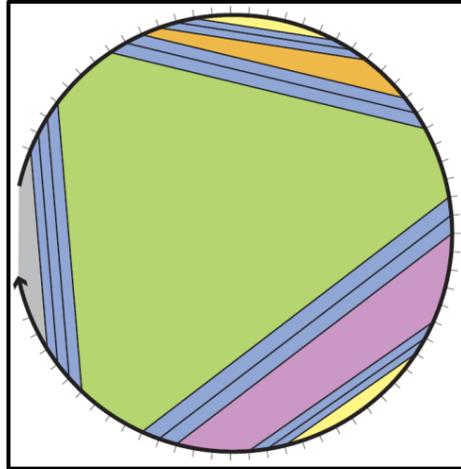
Initiation penalty

The Nearest Neighbour model for RNA/DNA

Single stranded system

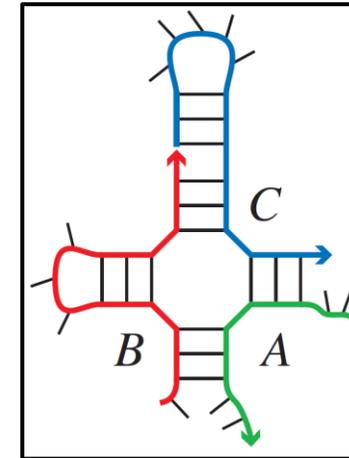


Dirks et al. 2007

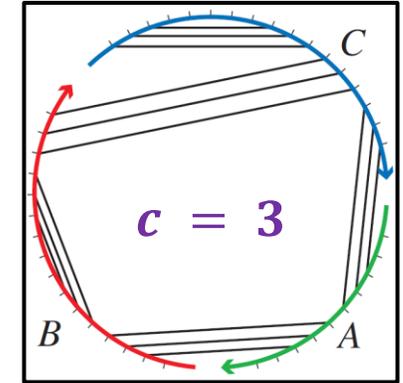


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Dirks et al. 2007



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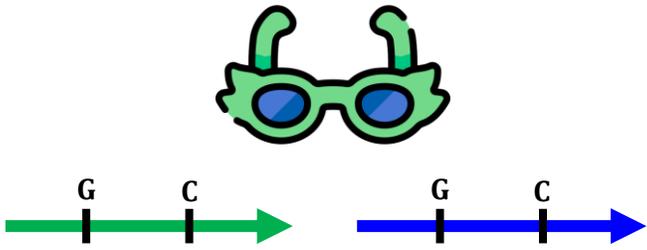
Initiation penalty

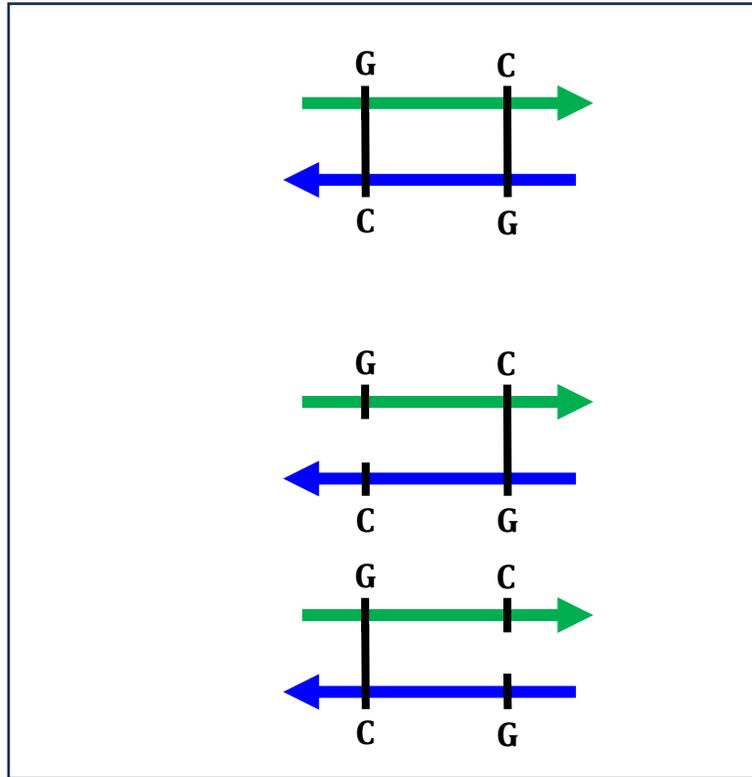
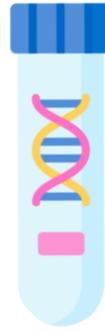
$$\text{MFE} = \min_{S \in \Omega} \Delta G(S)$$

Ω : the set of all **connected unpseudoknotted** secondary structures

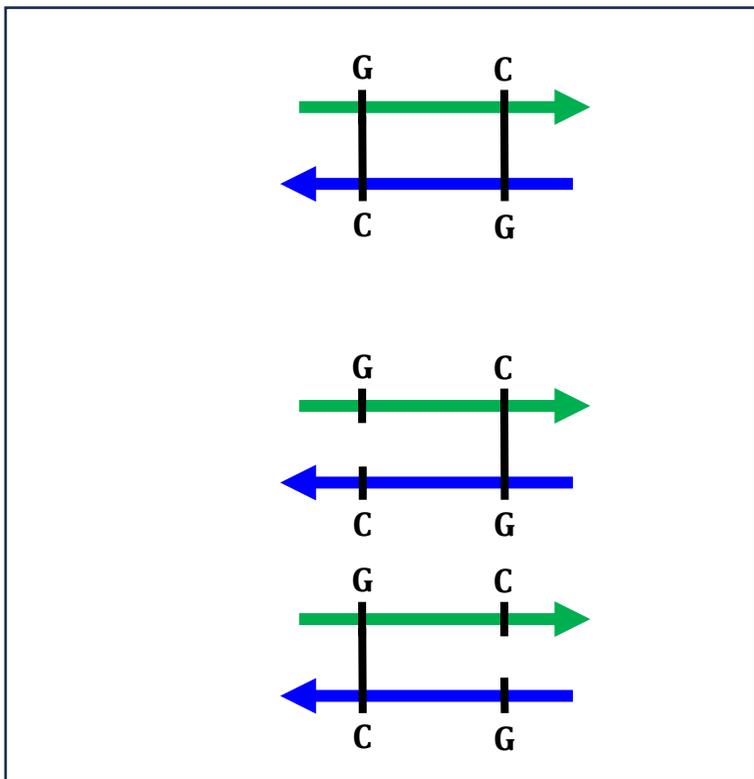




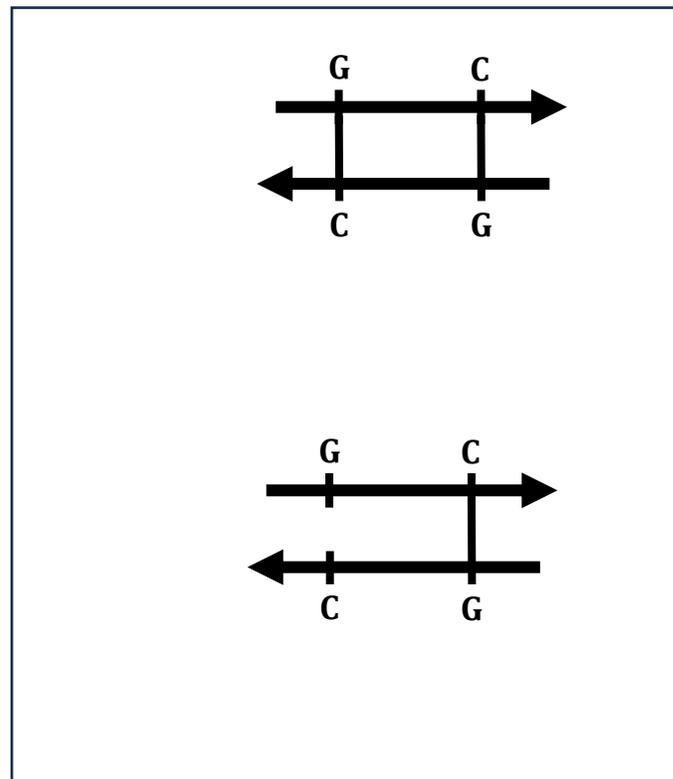
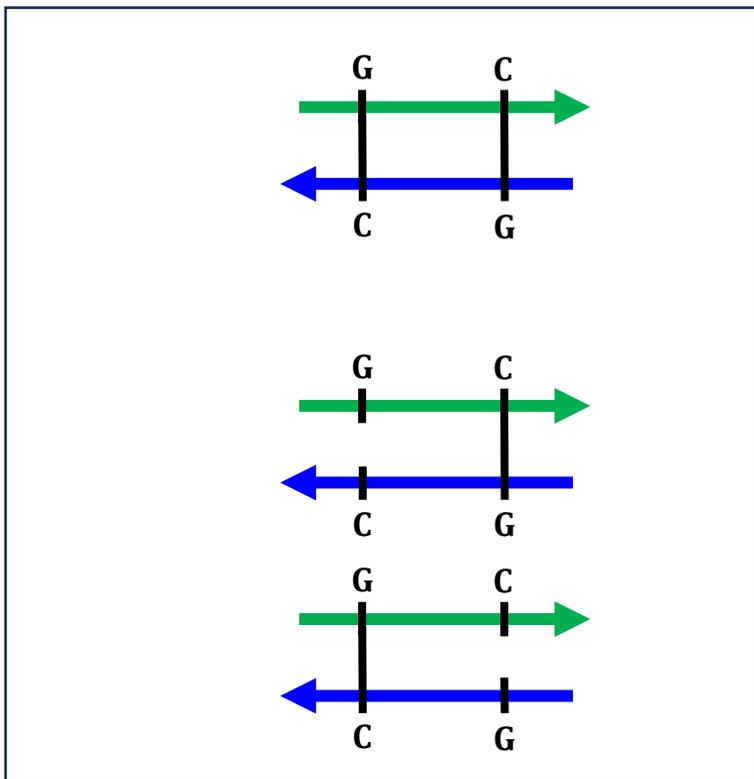




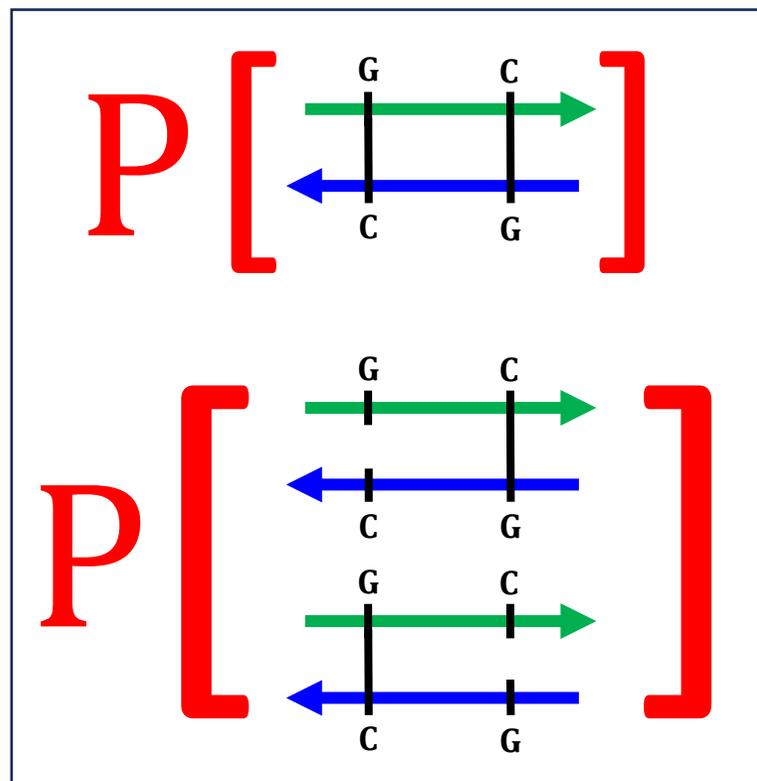
$$\Delta G(S) = \sum_l \Delta G(l) + (c - 1) \Delta G^{\text{assoc}}$$



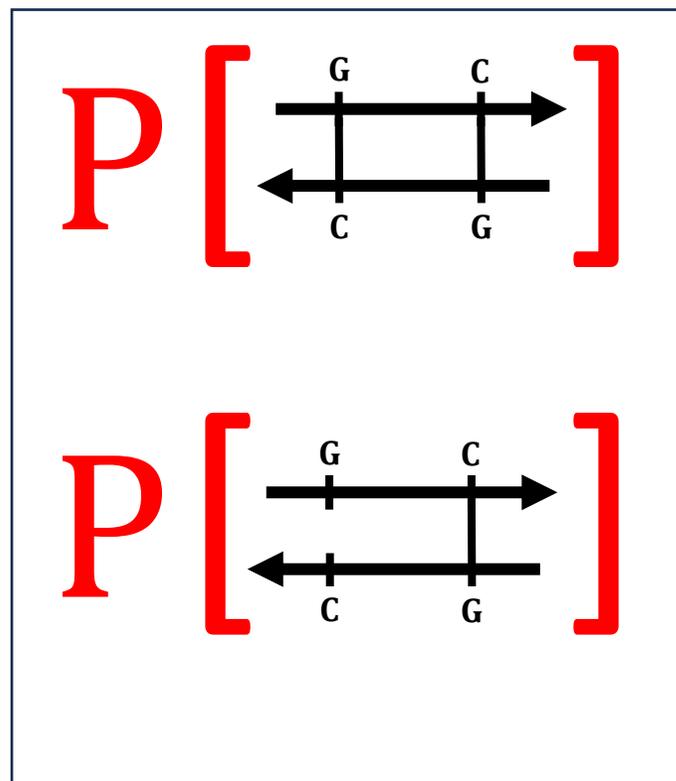
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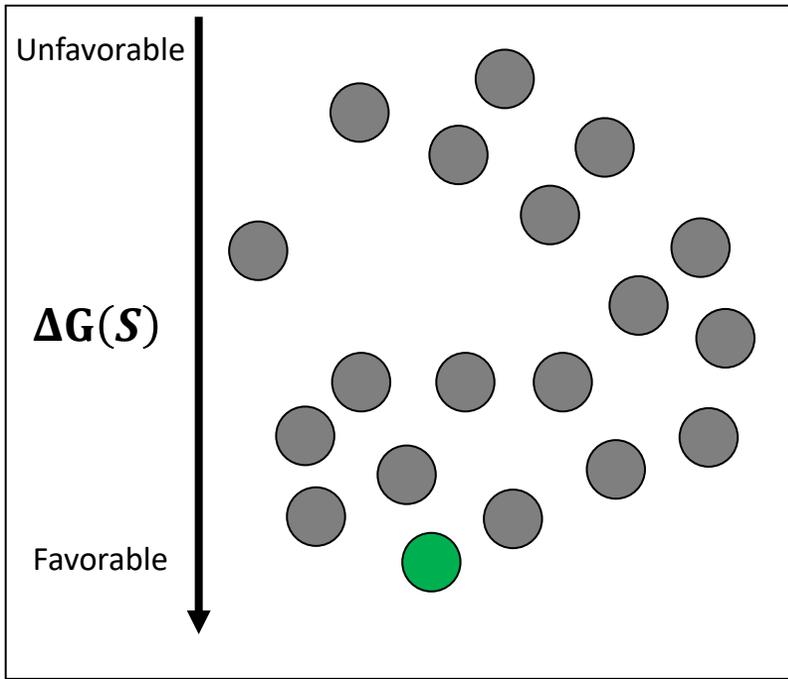


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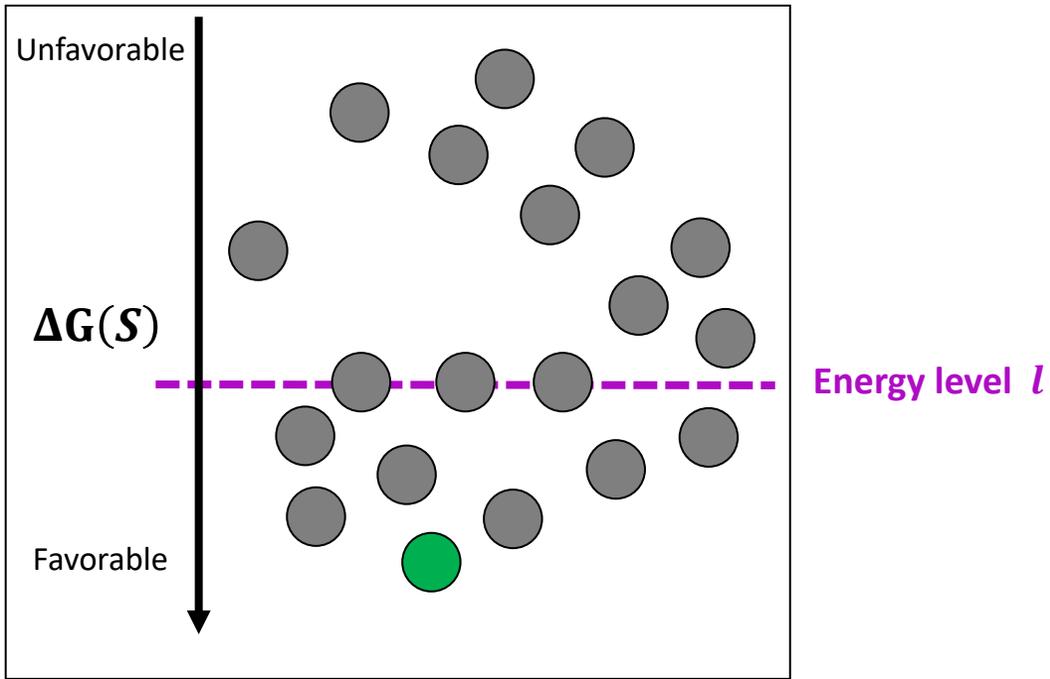


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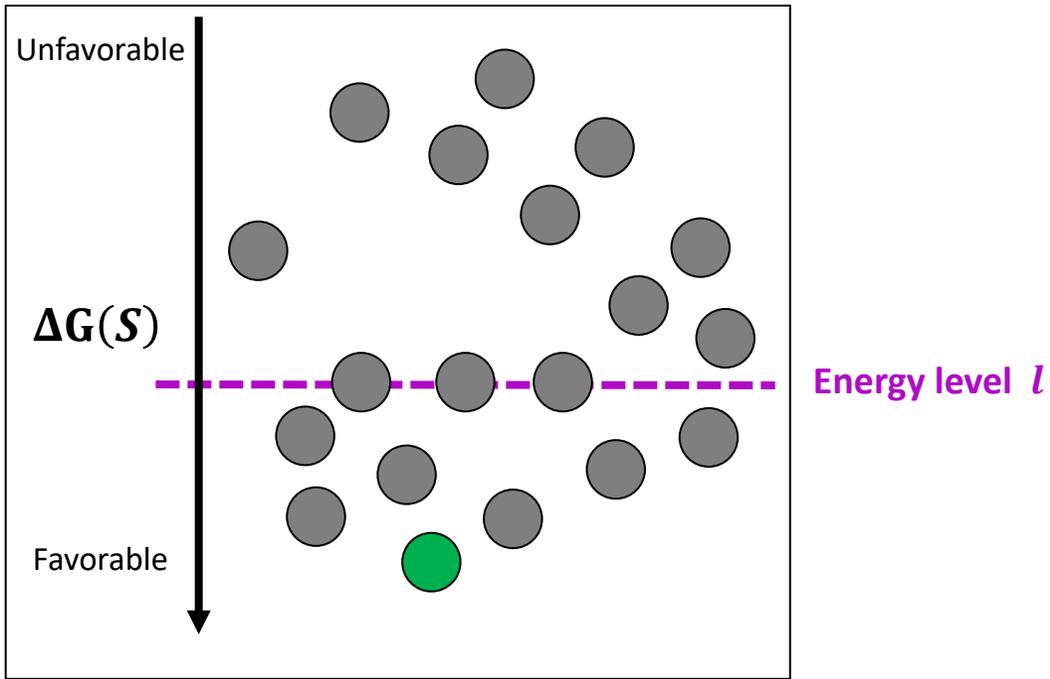
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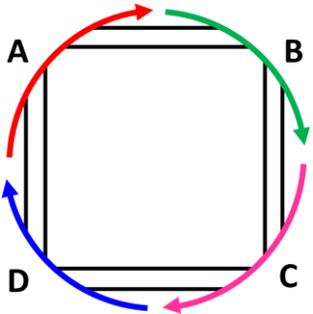
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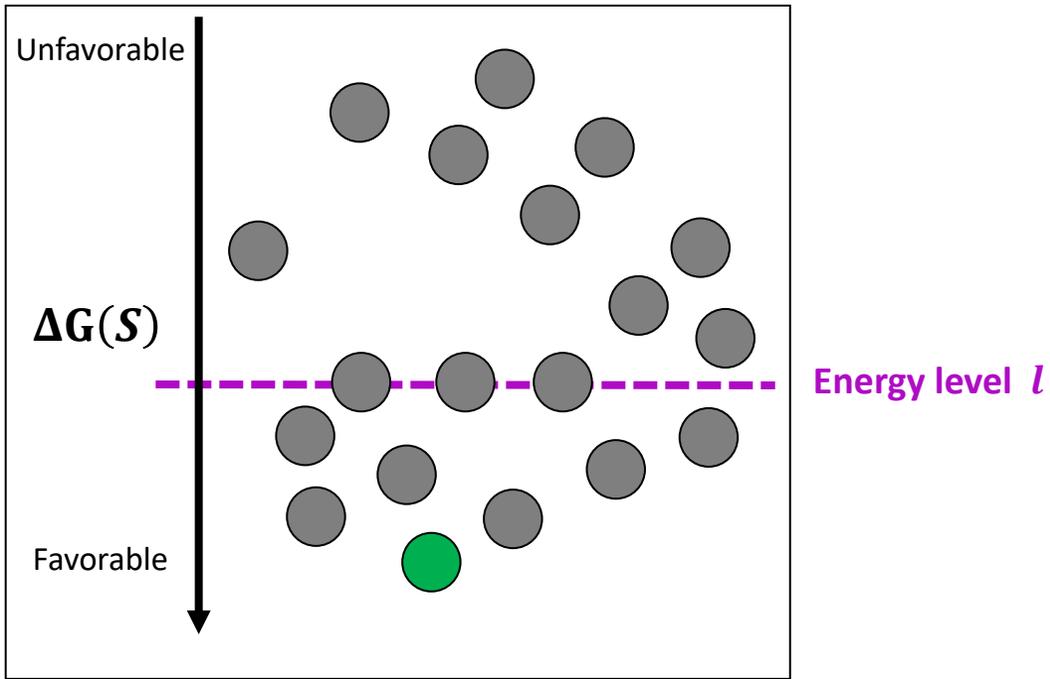


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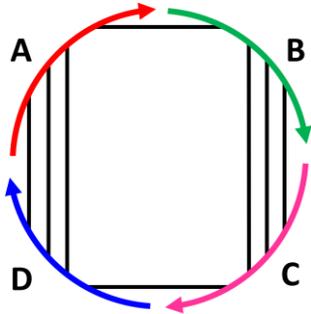
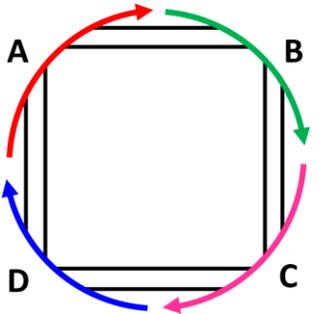


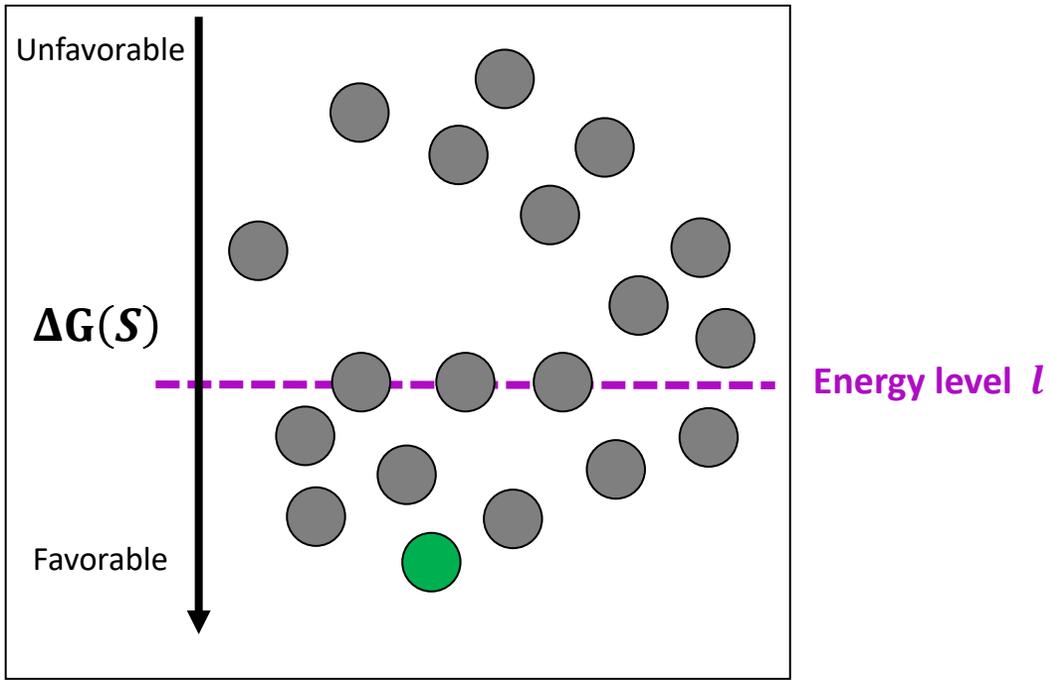
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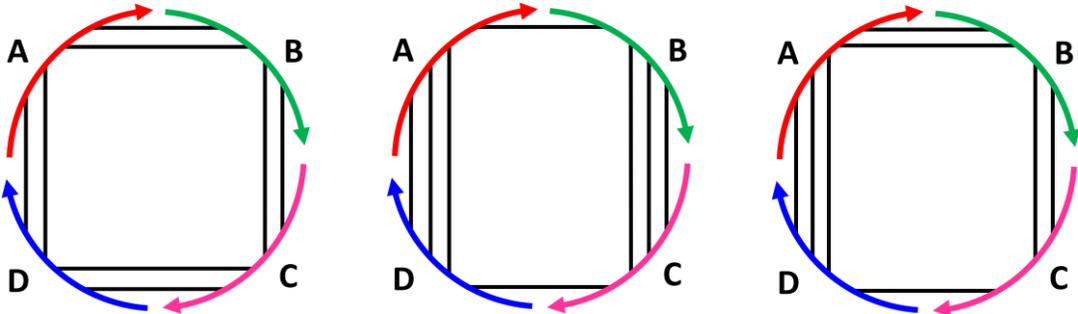


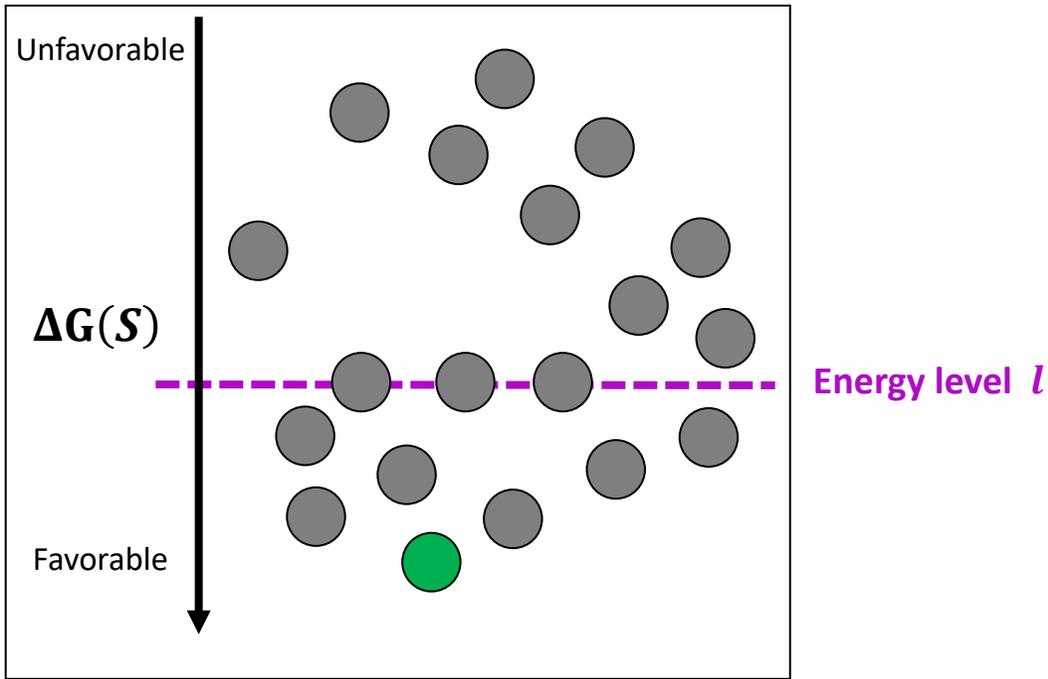
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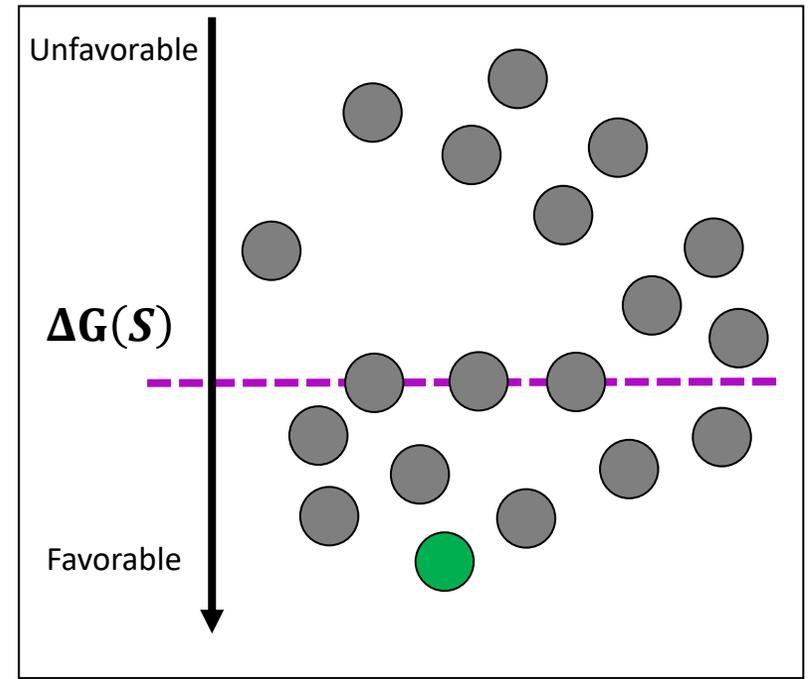


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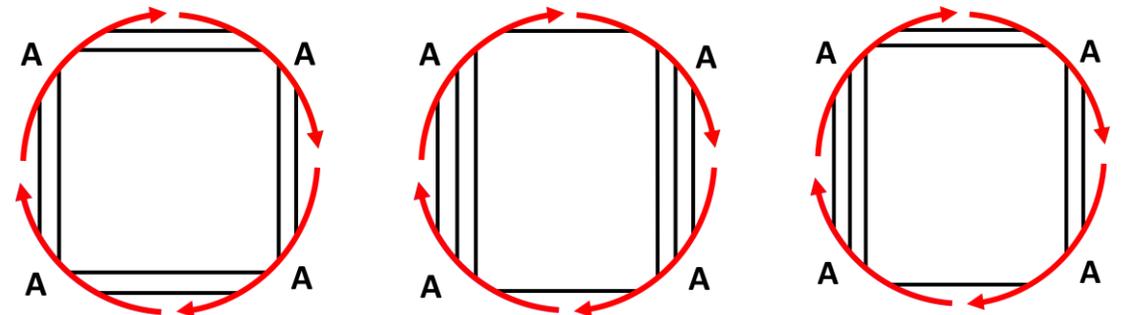
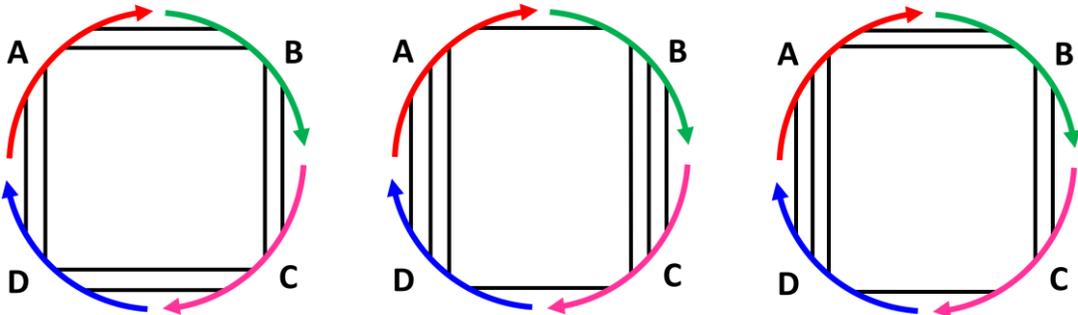


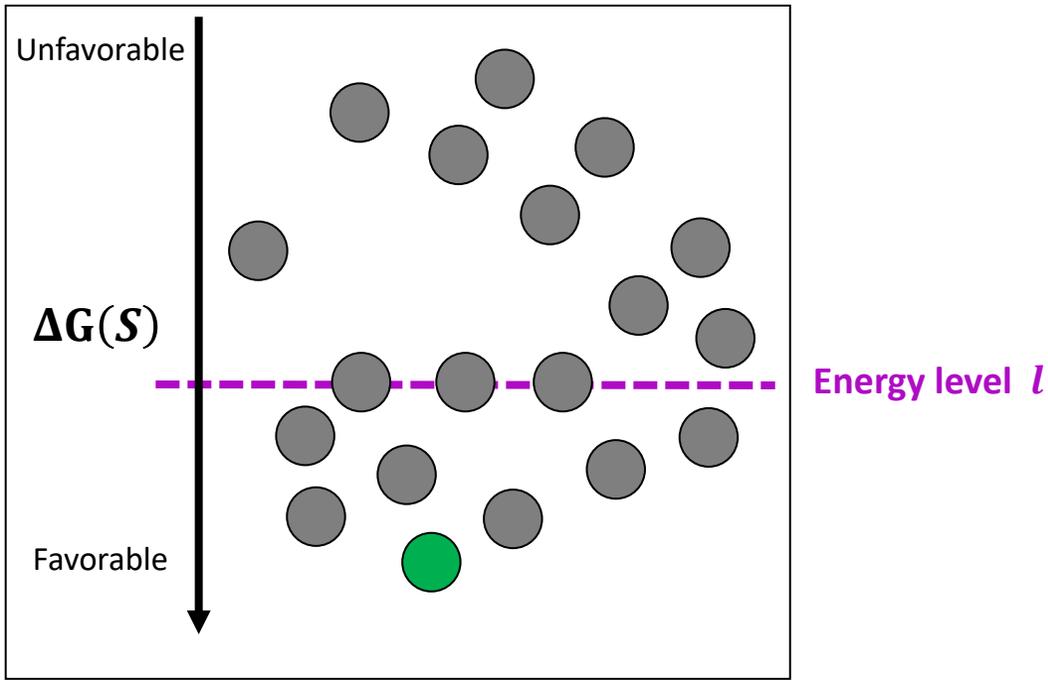
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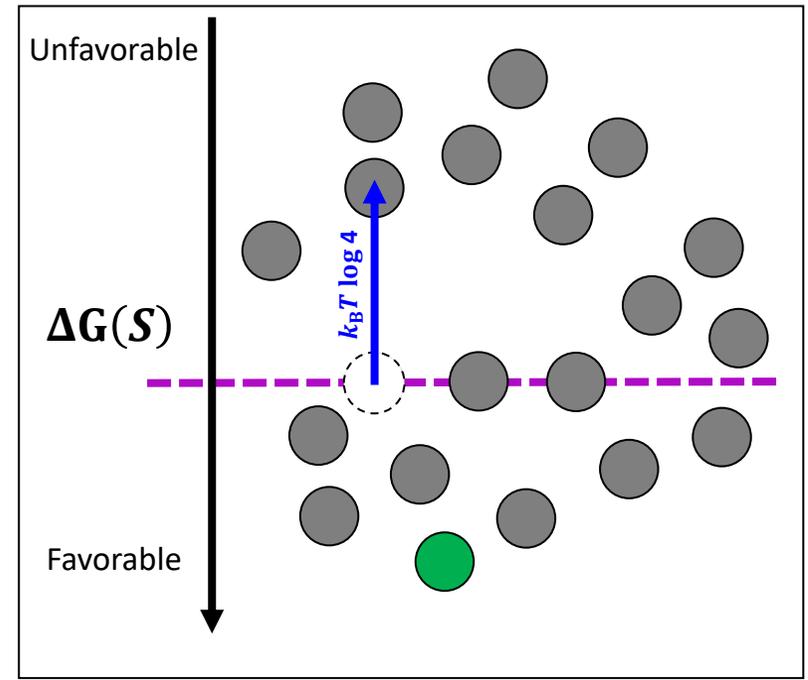
$$\Delta G(S) = \sum_l \Delta G(l) + (c - 1) \Delta G^{\text{assoc}} + k_B T \log R(S)$$

$R(S)$: degree of rotational symmetry of S



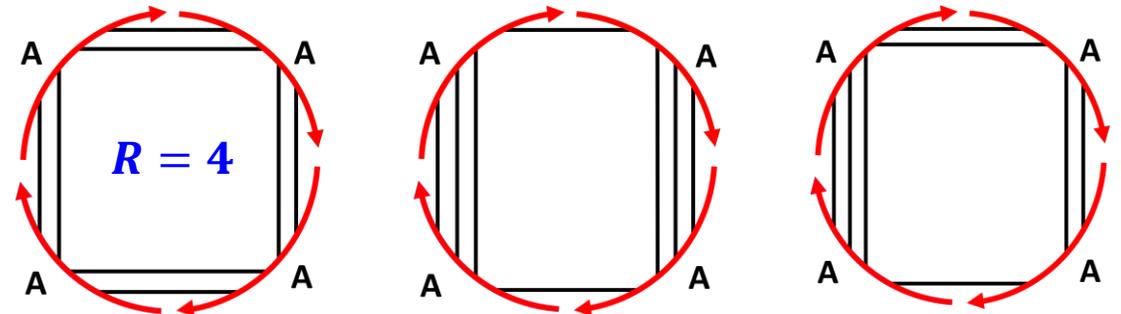
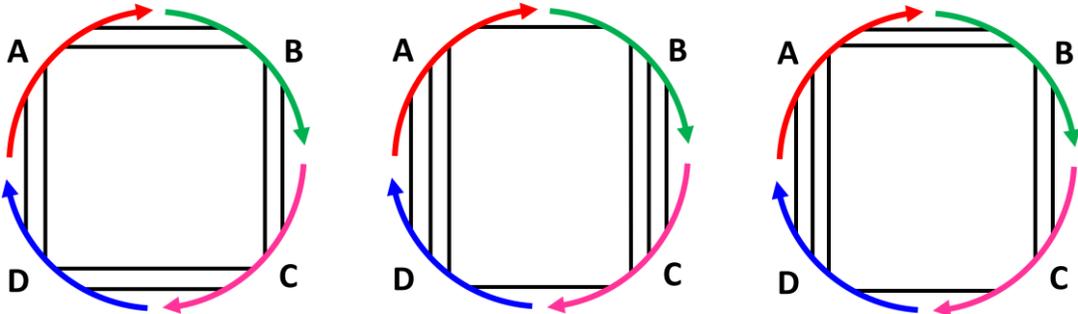


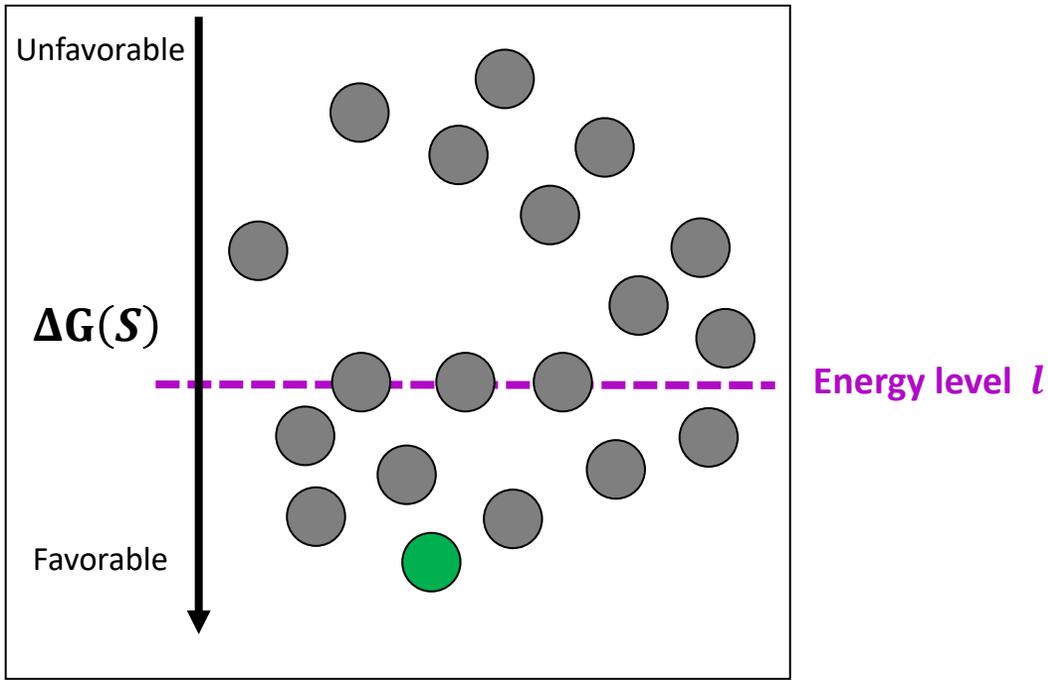
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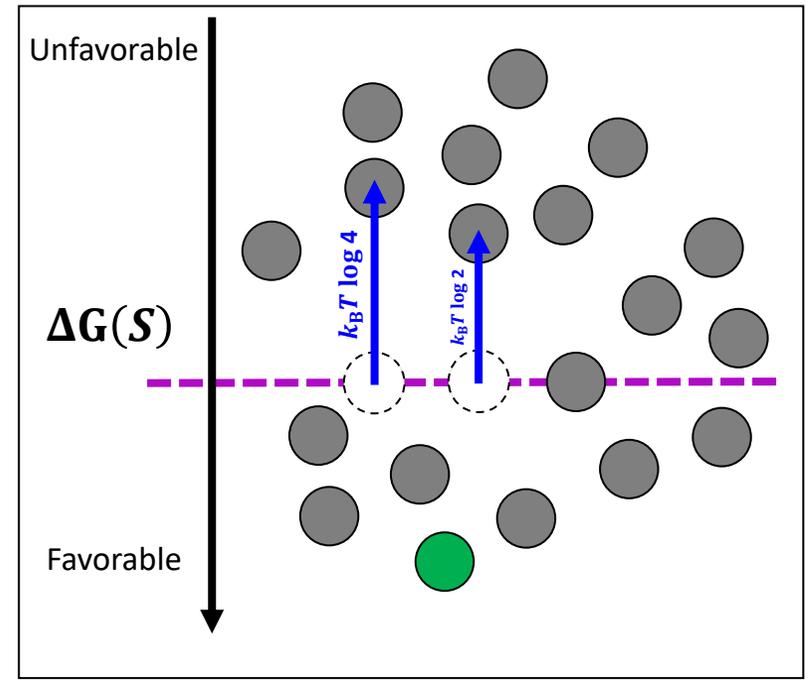
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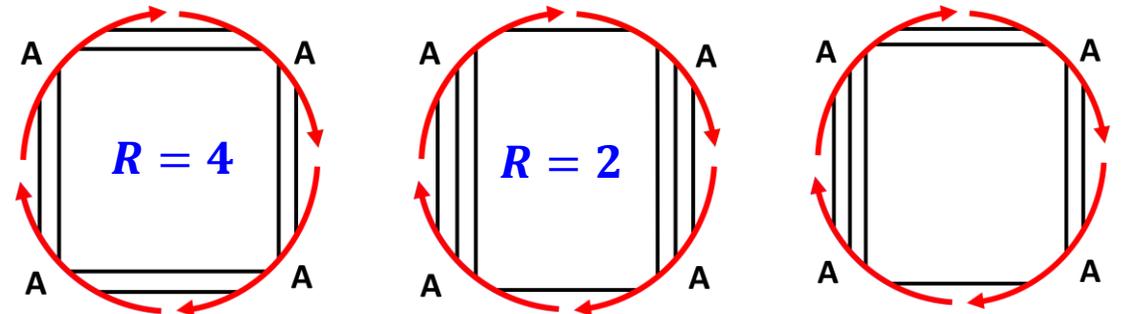
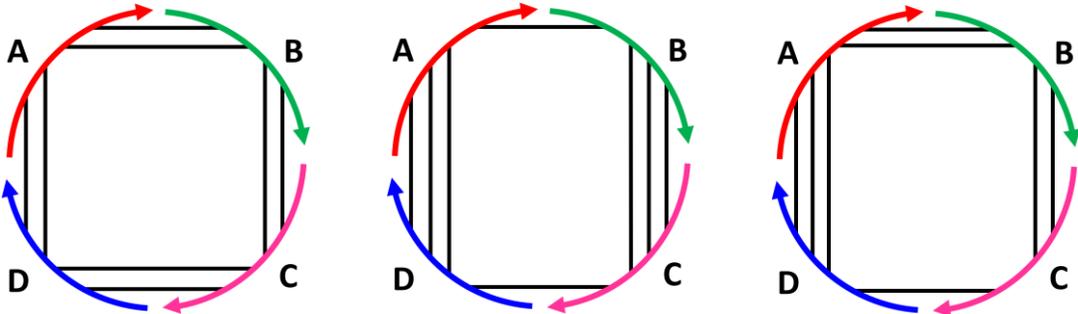


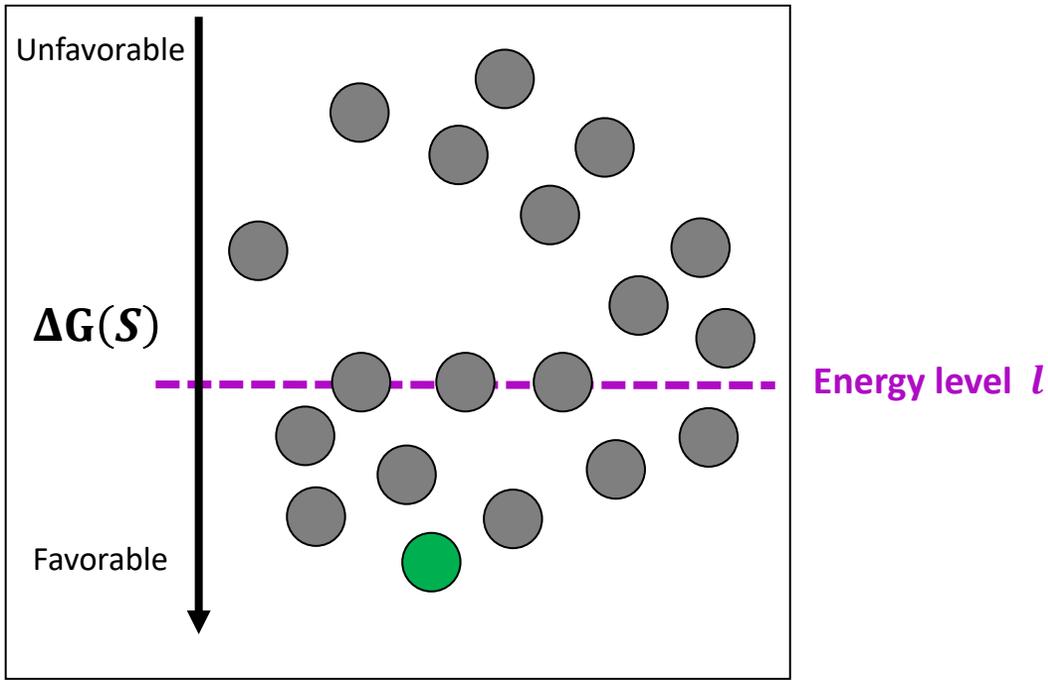
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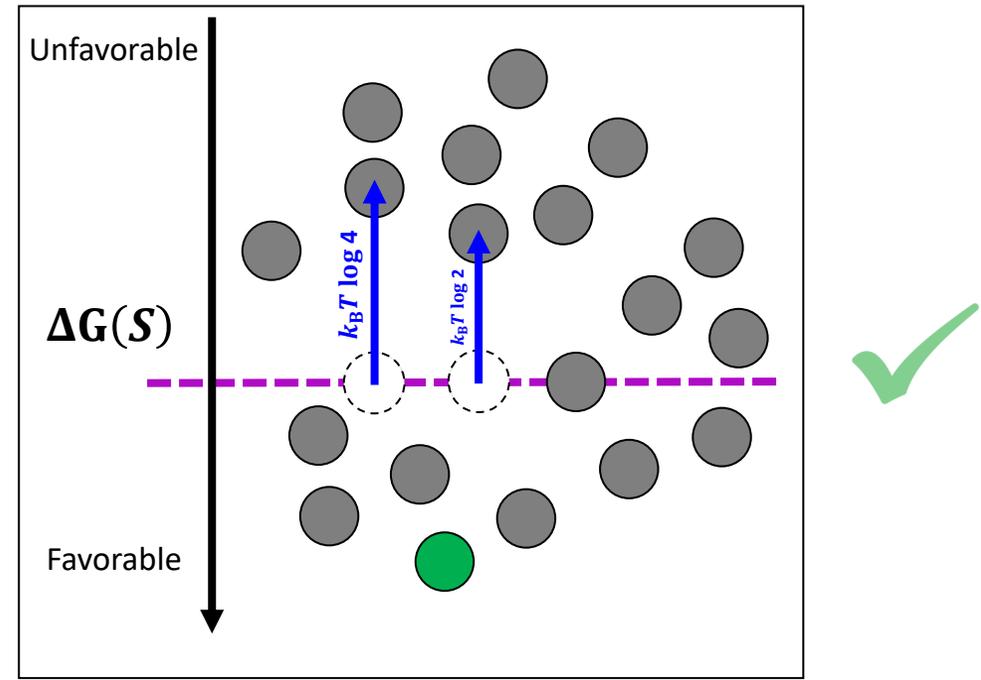
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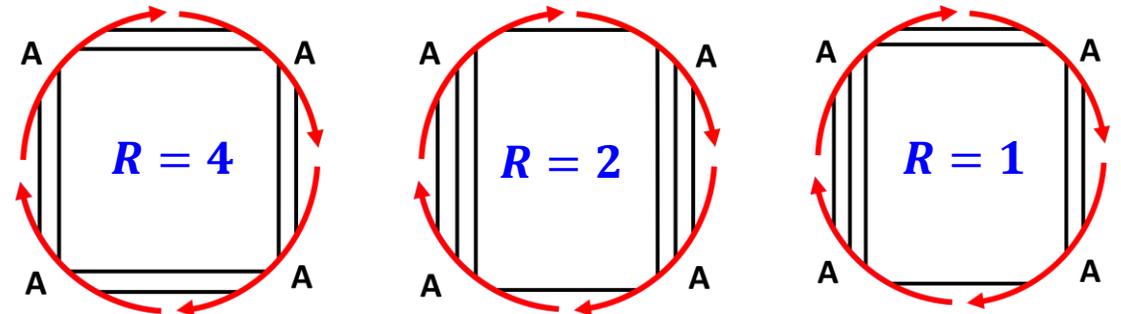
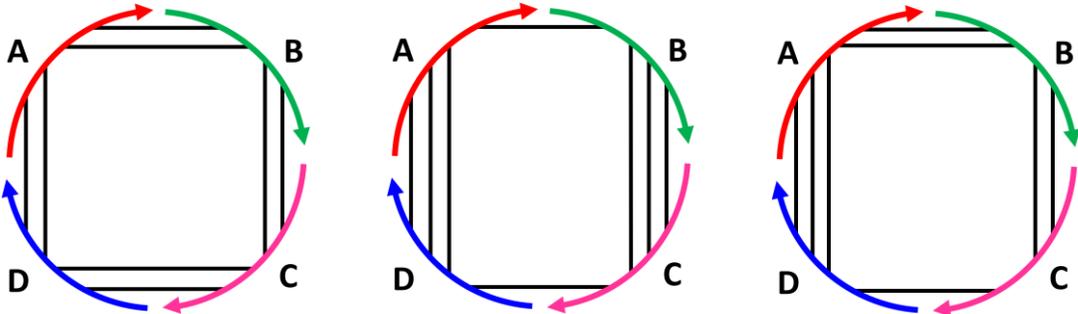


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Computational complexity of Minimum Free Energy

Input Type	MFE
Single strand	$O(N^3)$ <small>Nussinov et al. 1978</small>
$c = O(1)$ <u>unique</u> strands	$O(N^3(c - 1)!)$ <small>Dirks et al. 2007</small>
$c = O(1)$ <u>allowing repeated</u> strands	? Open problem for ≈ 20 years
Multiple strands, unbounded, $O(N)$ strands	NP – Complete <small>Condon, Hajiaghayi, Thachuk 2021</small>

N bases, c strands

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Subproblems



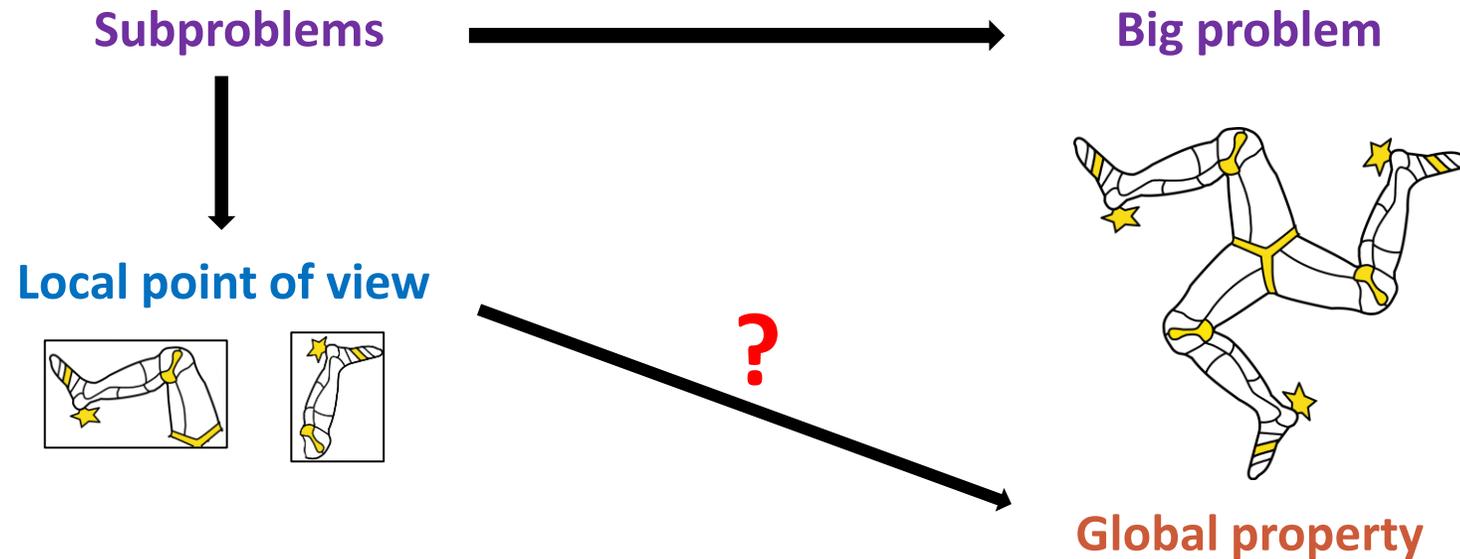
Big problem

Computational complexity of Minimum Free Energy

Input Type	MFE
Single strand	$O(N^3)$ <small>Nussinov et al. 1978</small>
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} **Dynamic programming algorithms**

N bases, c strands



Current state of art

Input Type	MFE
Single strand	$O(N^3)$
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N bases, c strands

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N bases, c strands

Goal

$$\Delta G(S) = \sum_l \Delta G(l) + (c - 1)\Delta G^{\text{assoc}} + k_B T \log R(S)$$

$$\text{MFE} = \min_{S \in \Omega} \Delta G(S)$$

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N bases, c strands

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 NUPACK




N bases, c strands

$$\overline{\Delta G}(S) = \sum_l \Delta G(l) + (c - 1) \Delta G^{\text{assoc}}$$

Symmetry naive energy function

$$\text{snMFE} = \min_{S \in \Omega} \overline{\Delta G}(S)$$

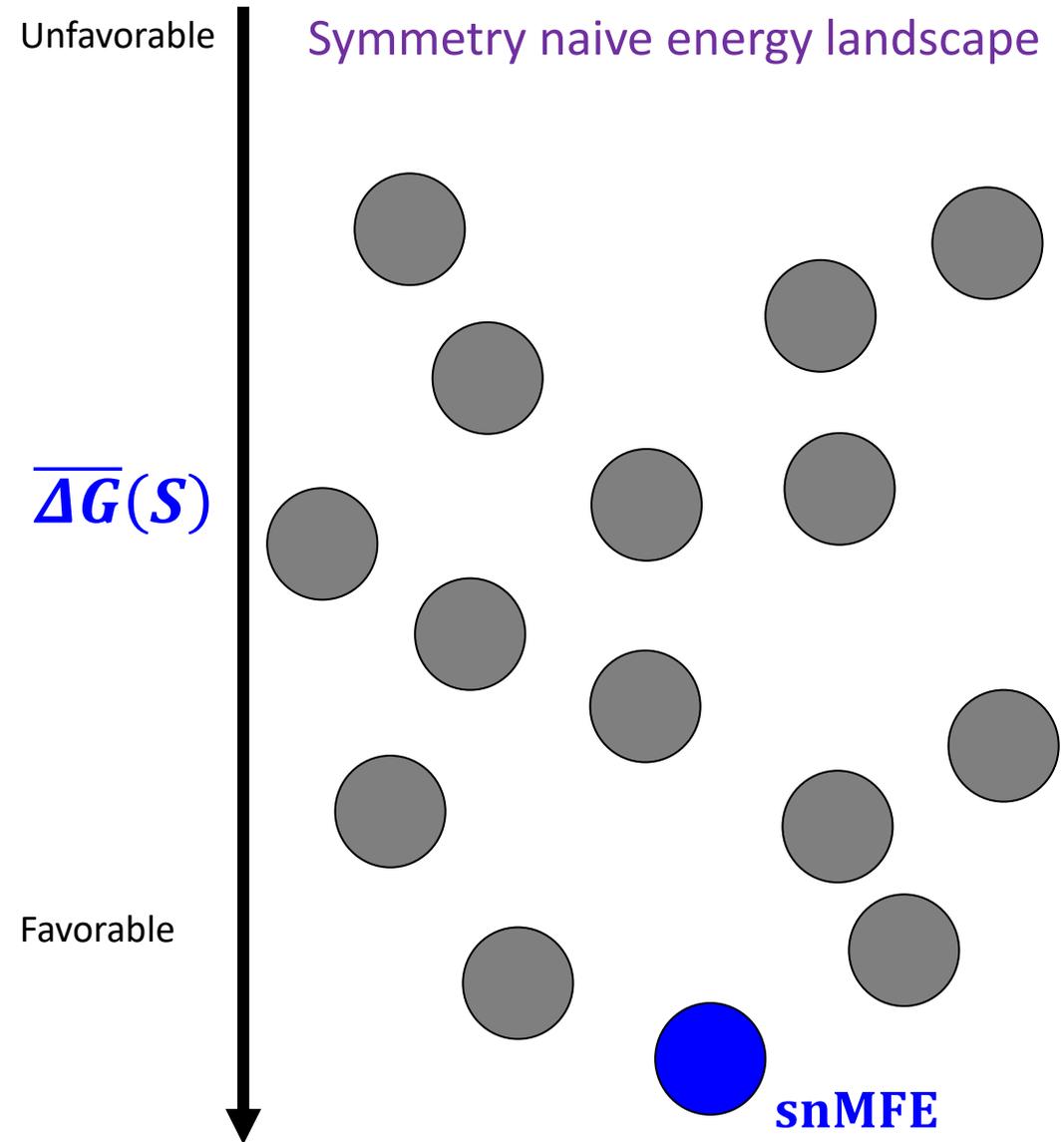
Symmetry naive MFE

Goal

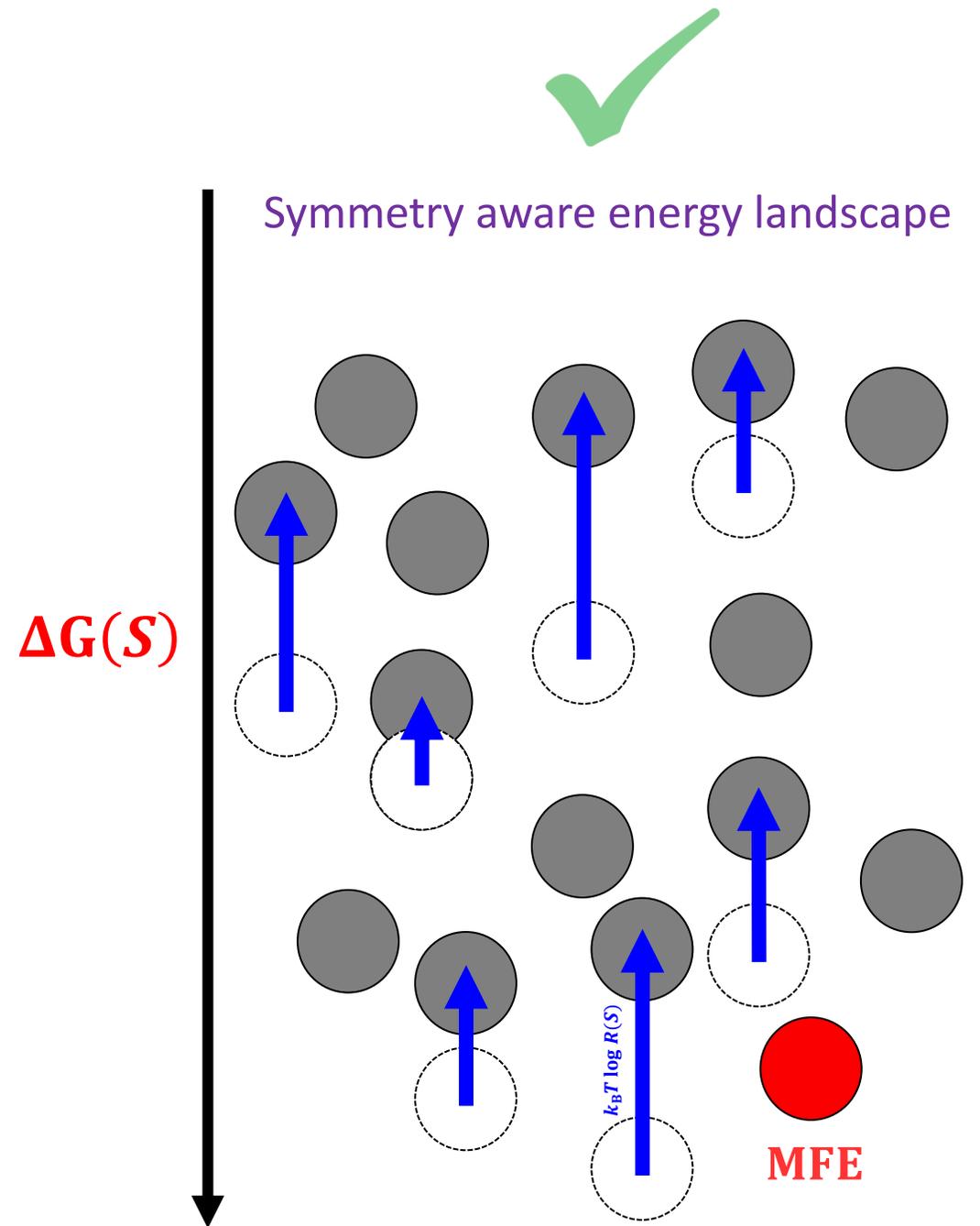
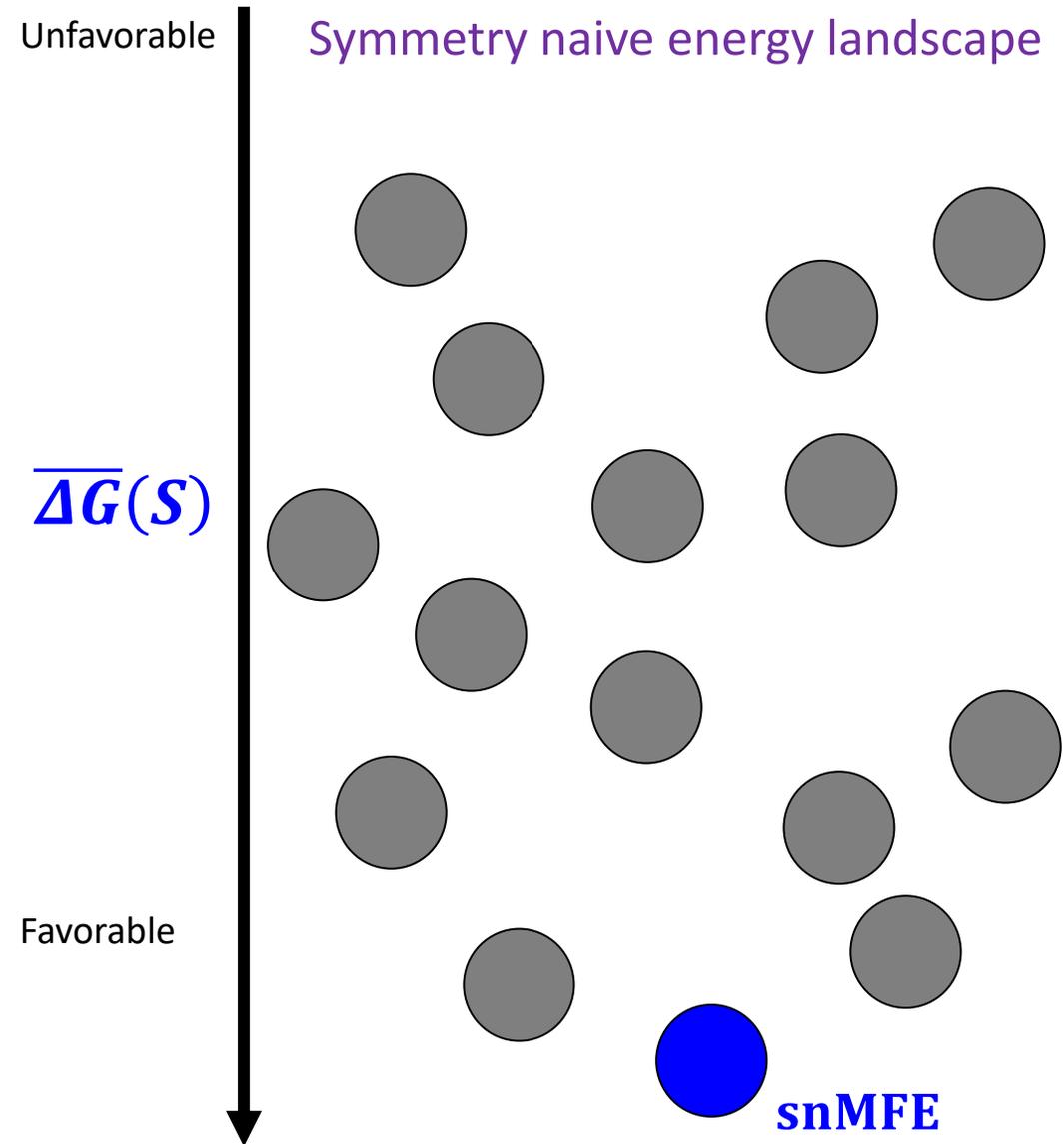
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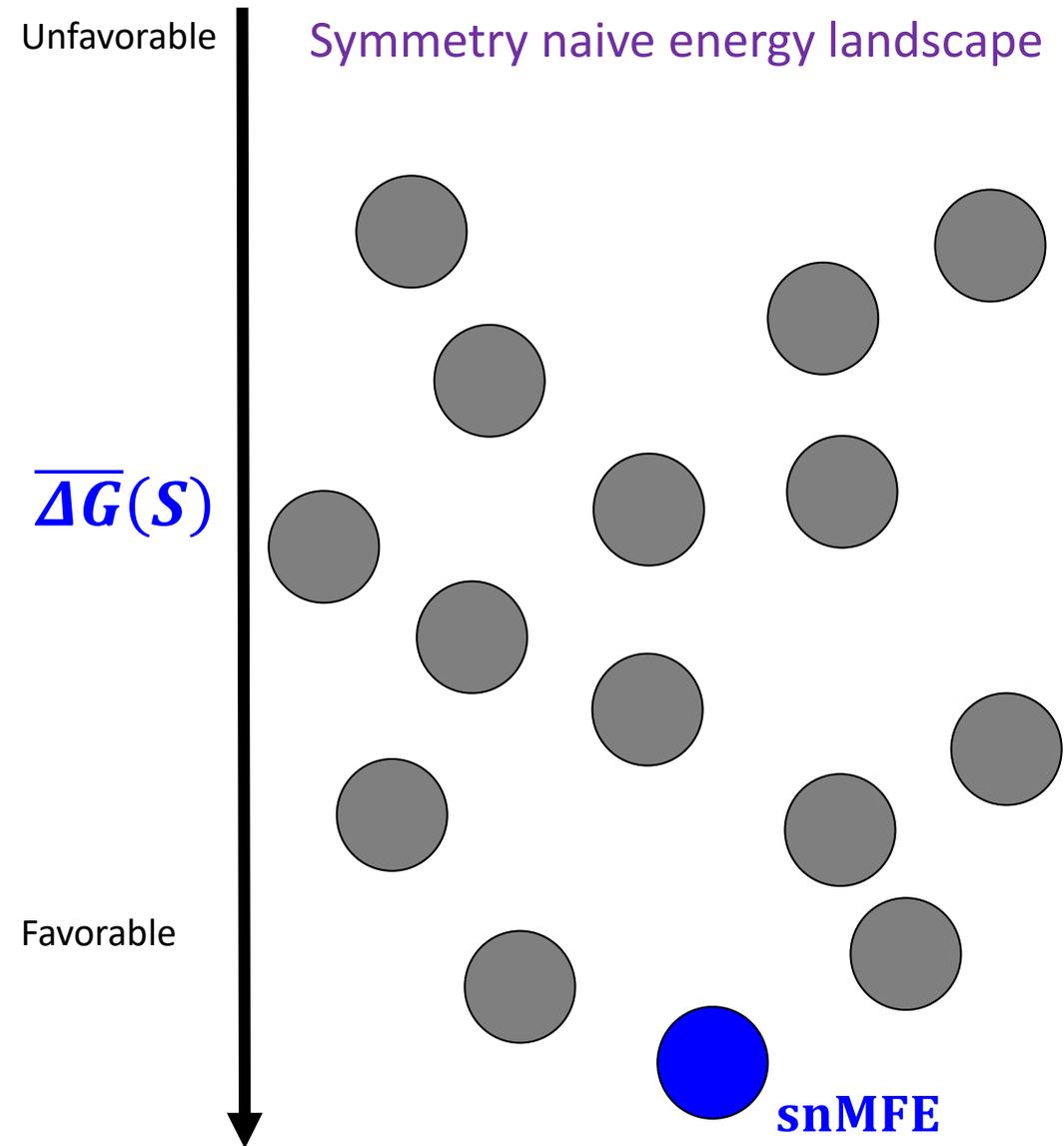
Current state of art



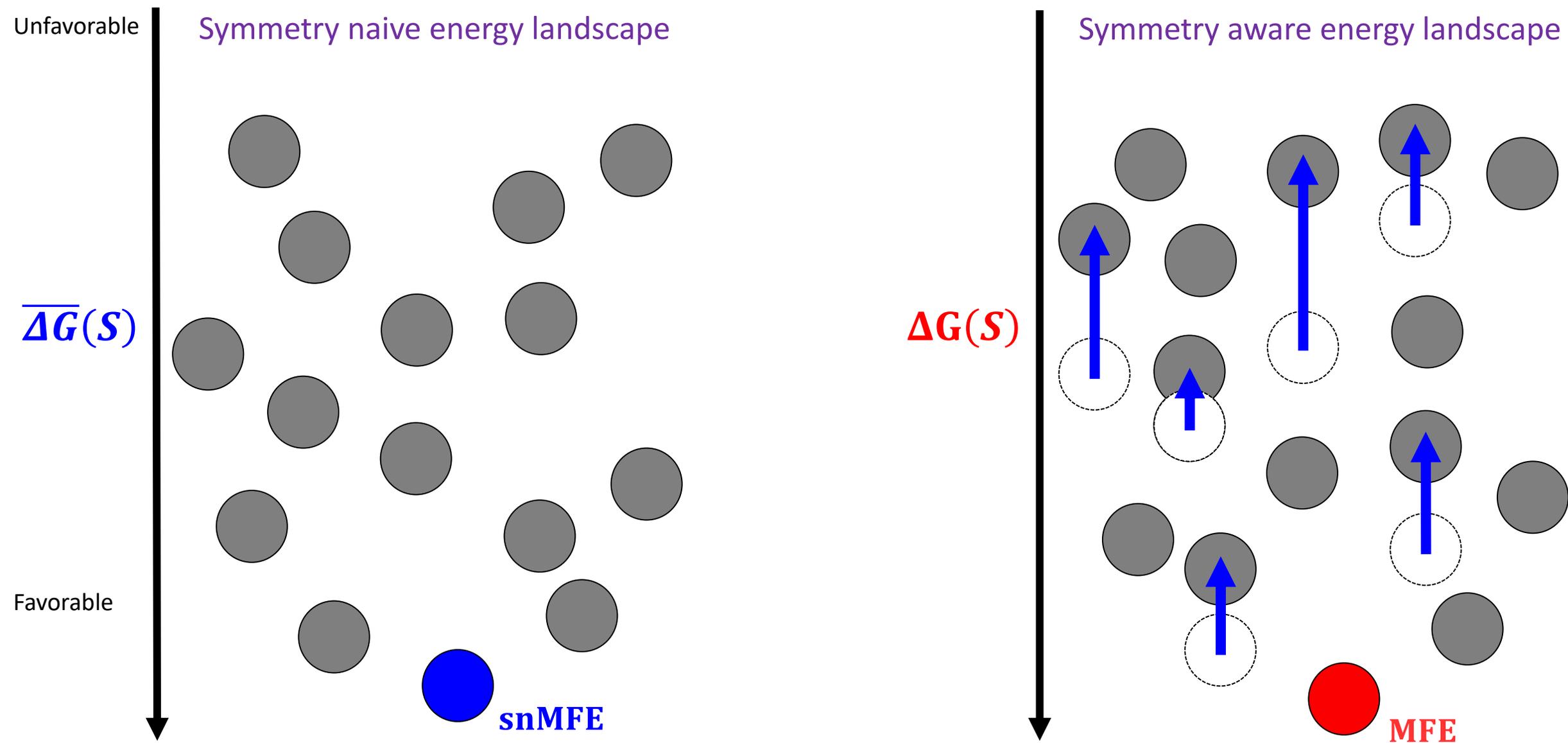
Current state of art



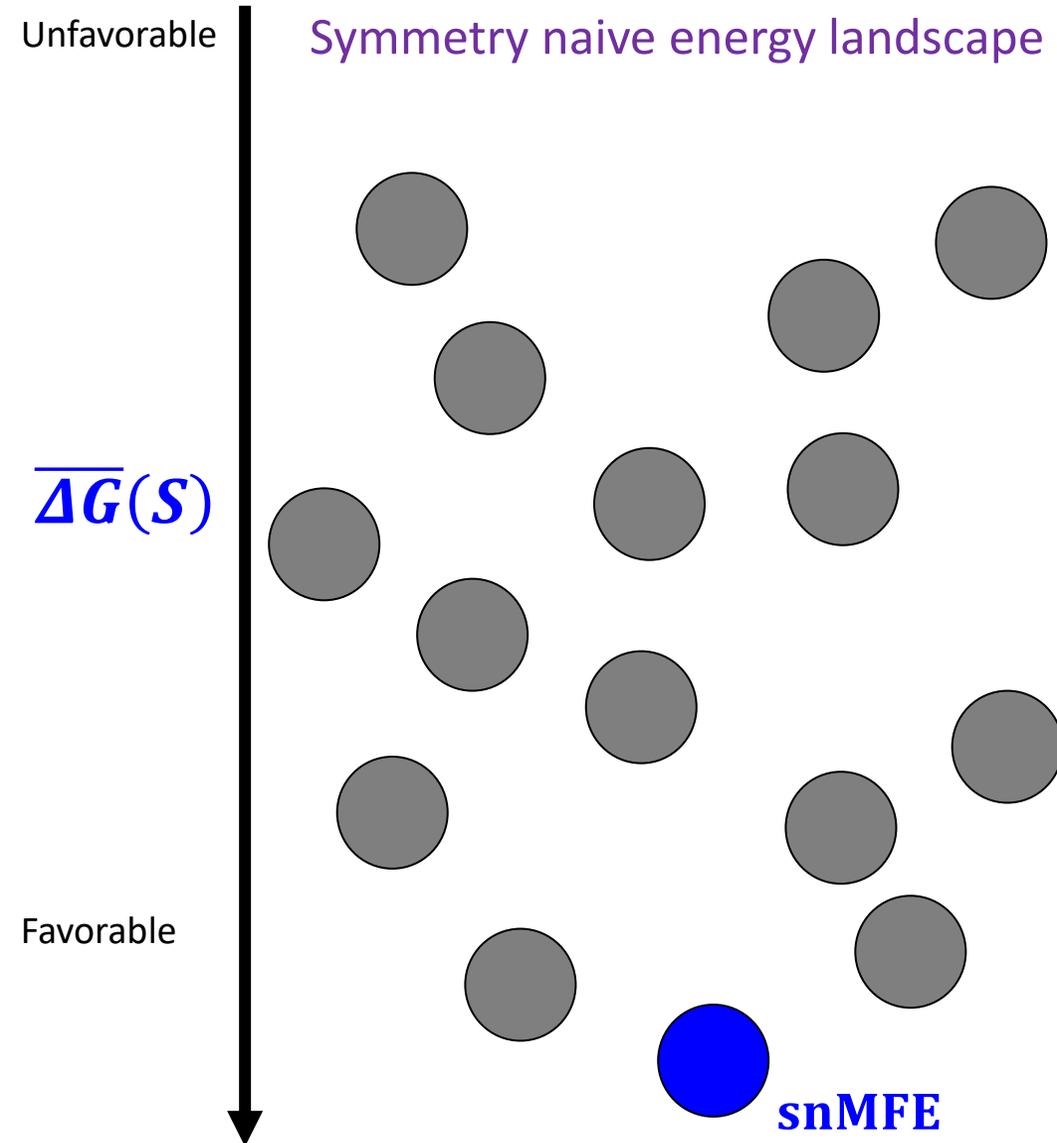
If **snMFE** structure is Asymmetric ($R = 1$)



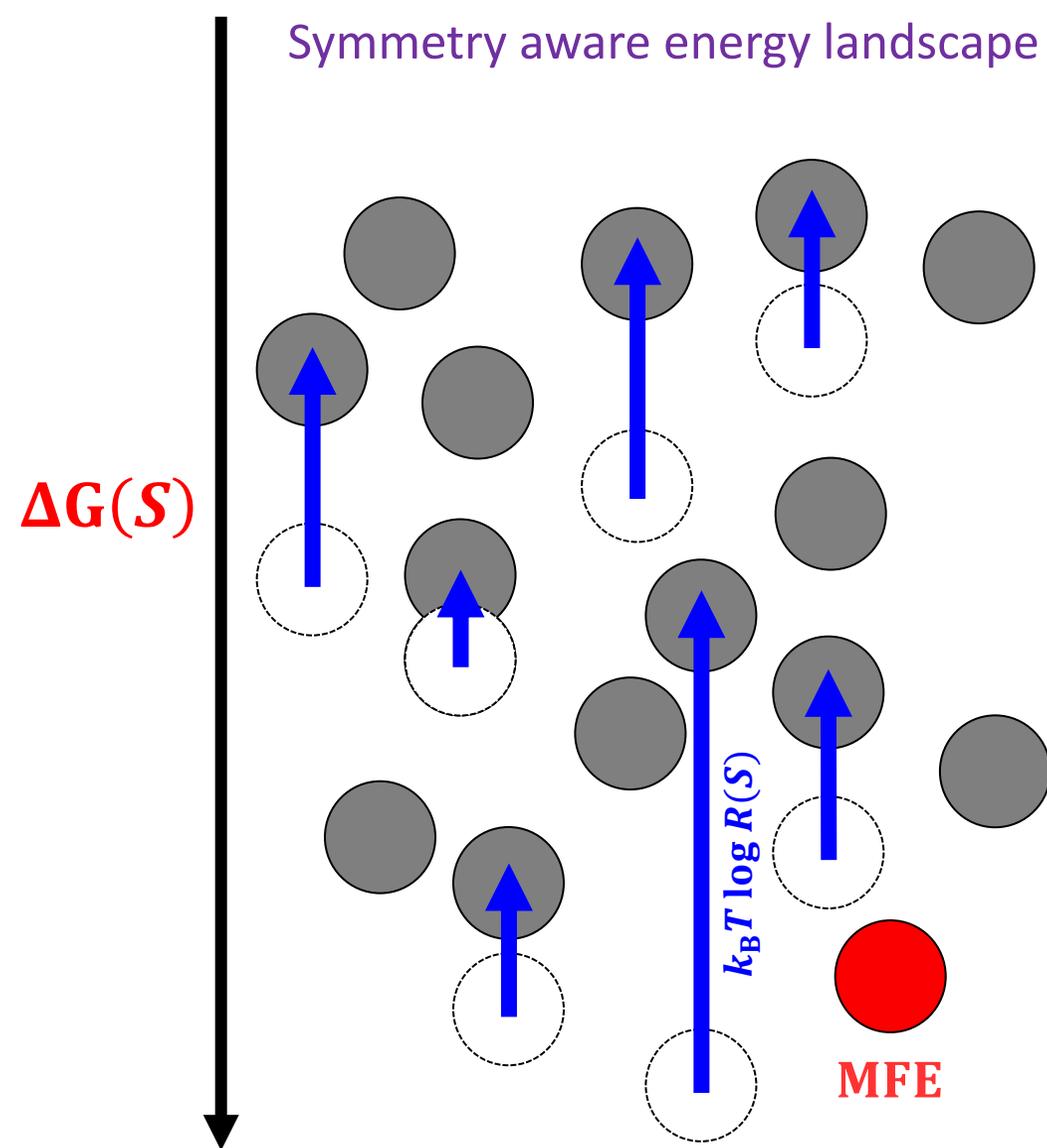
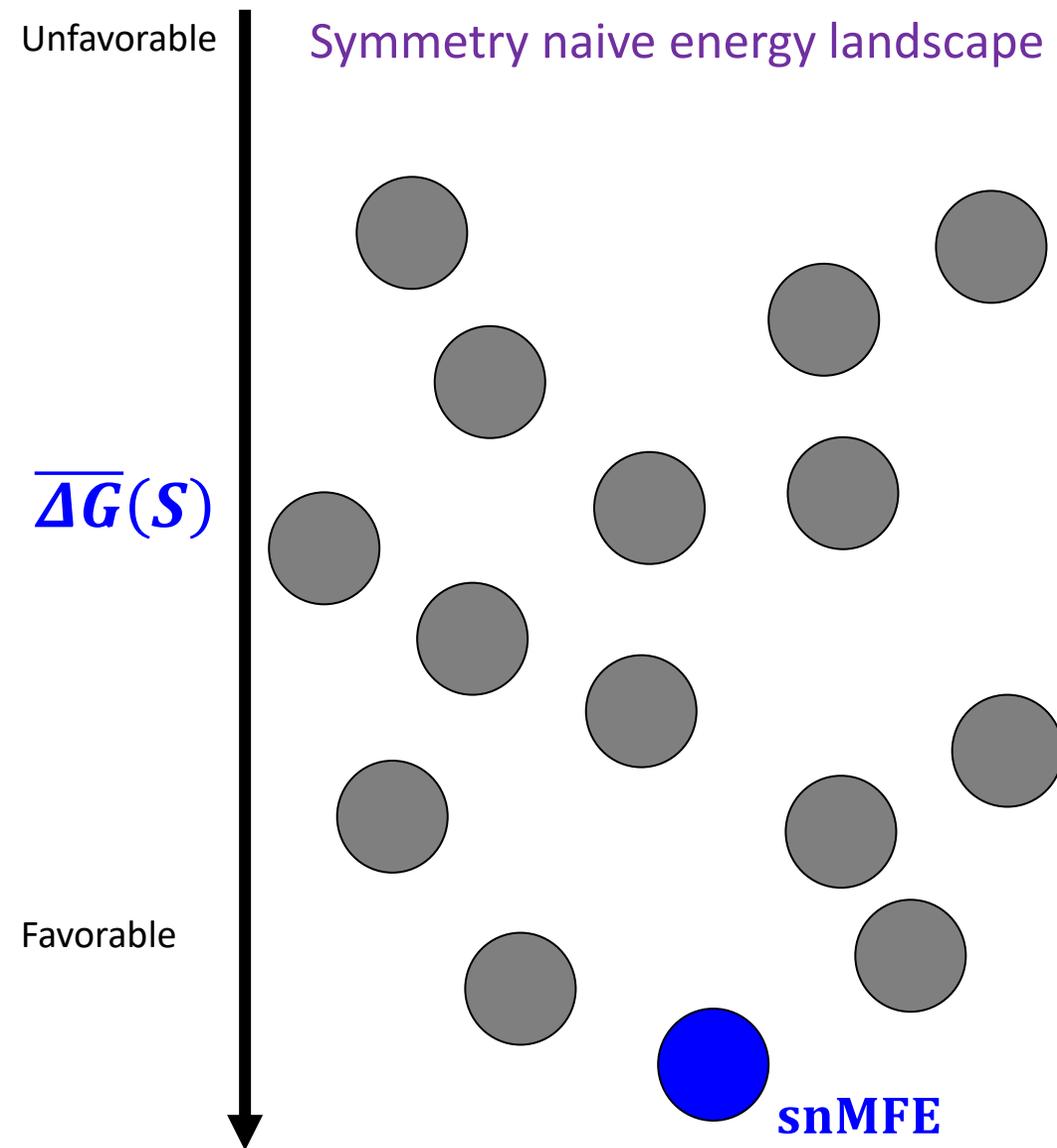
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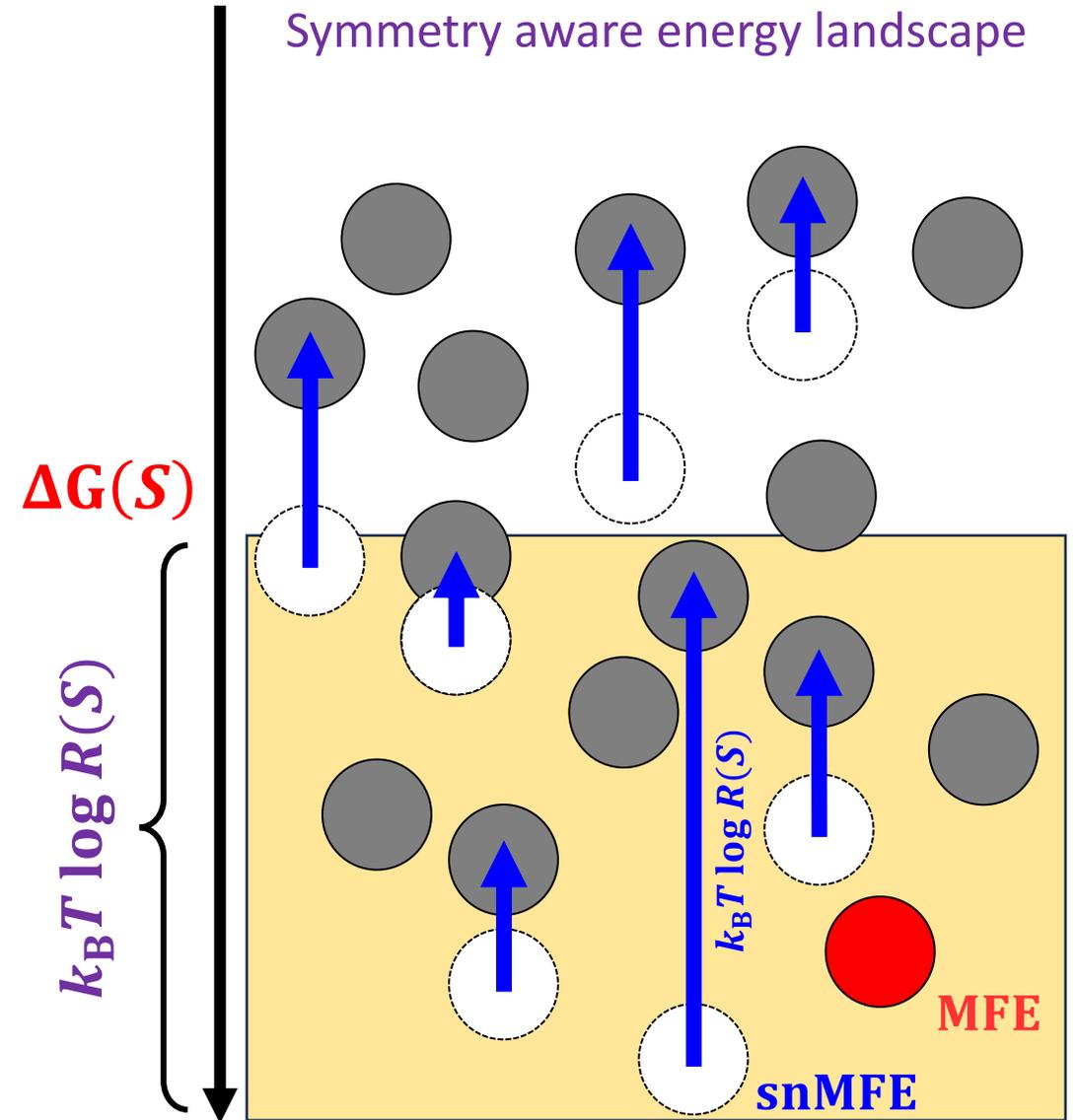
If **snMFE** structure is Symmetric ($R > 1$)



If **snMFE** structure is Symmetric ($R > 1$)

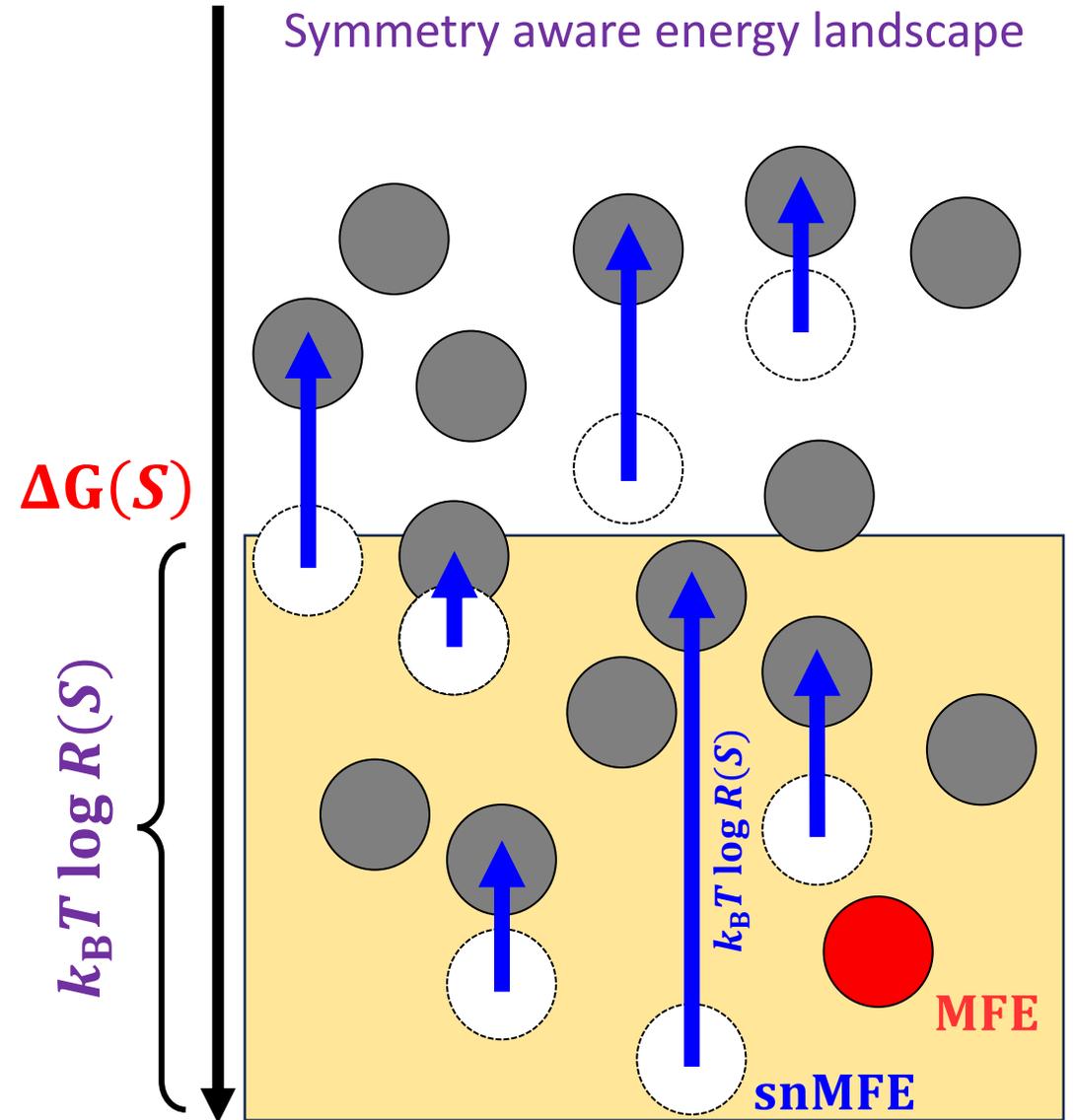
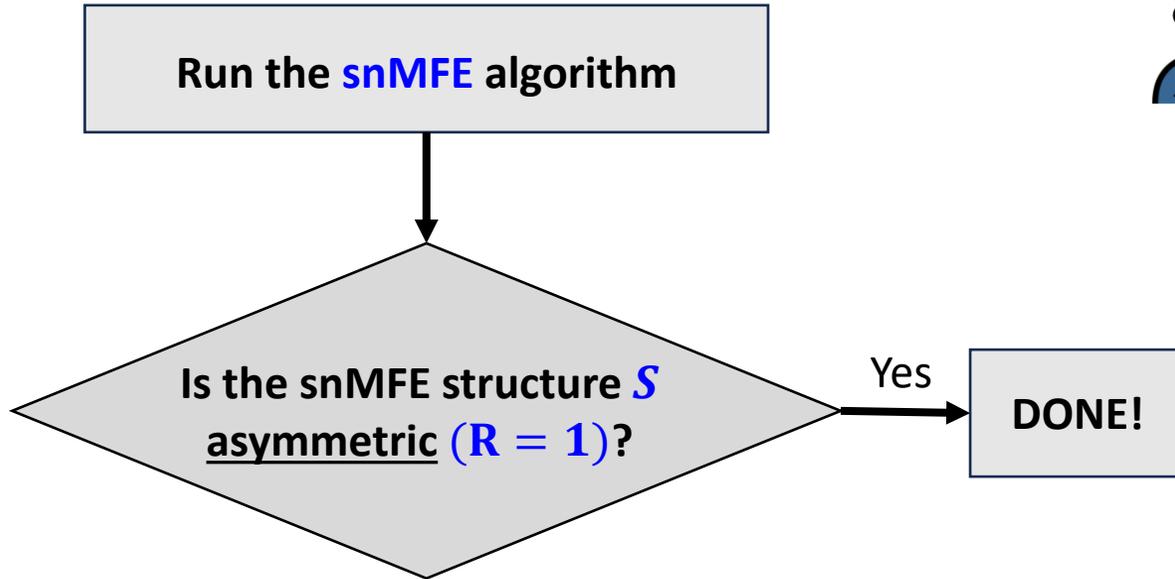


If snMFE structure is Symmetric ($R > 1$)



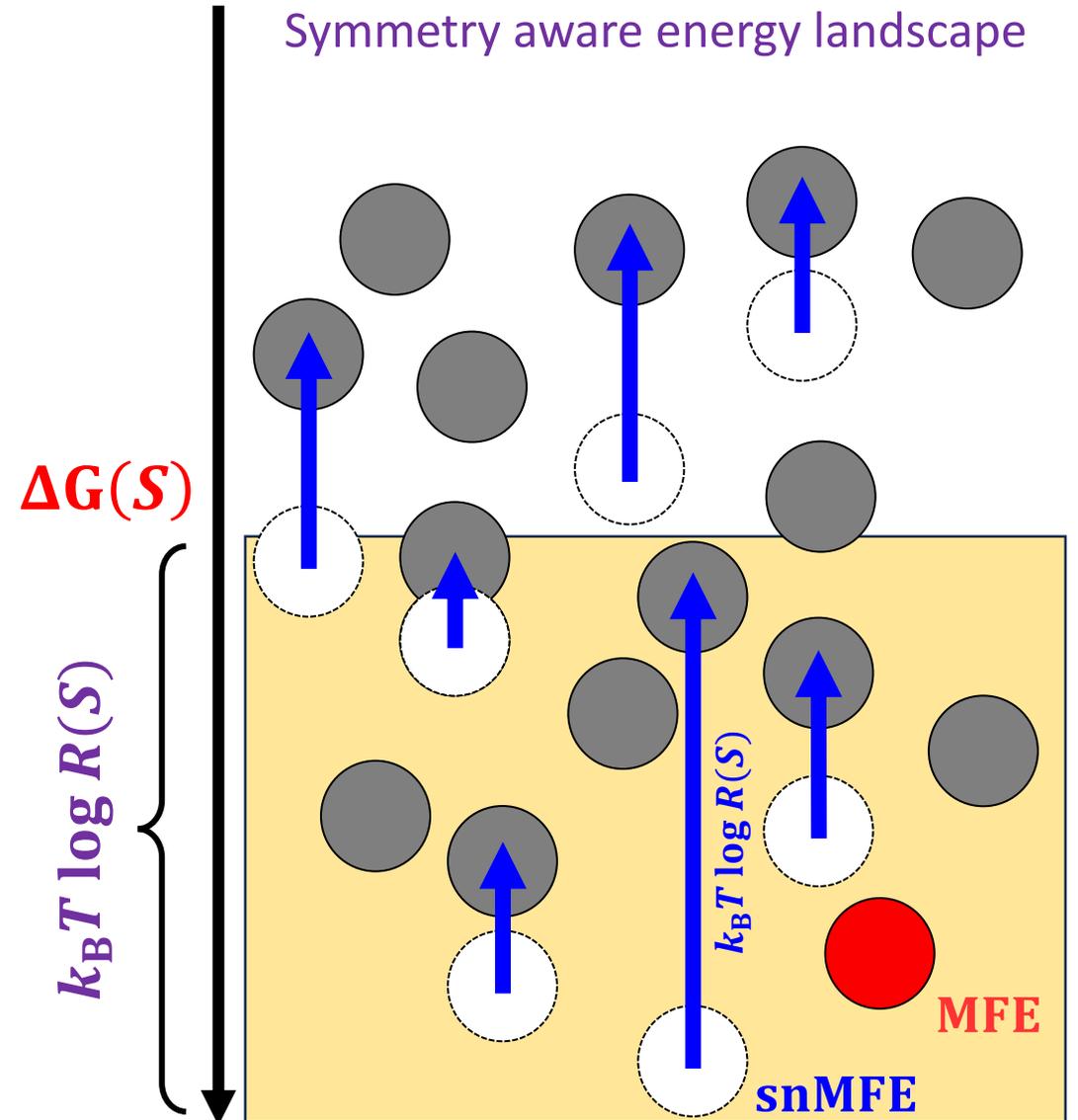
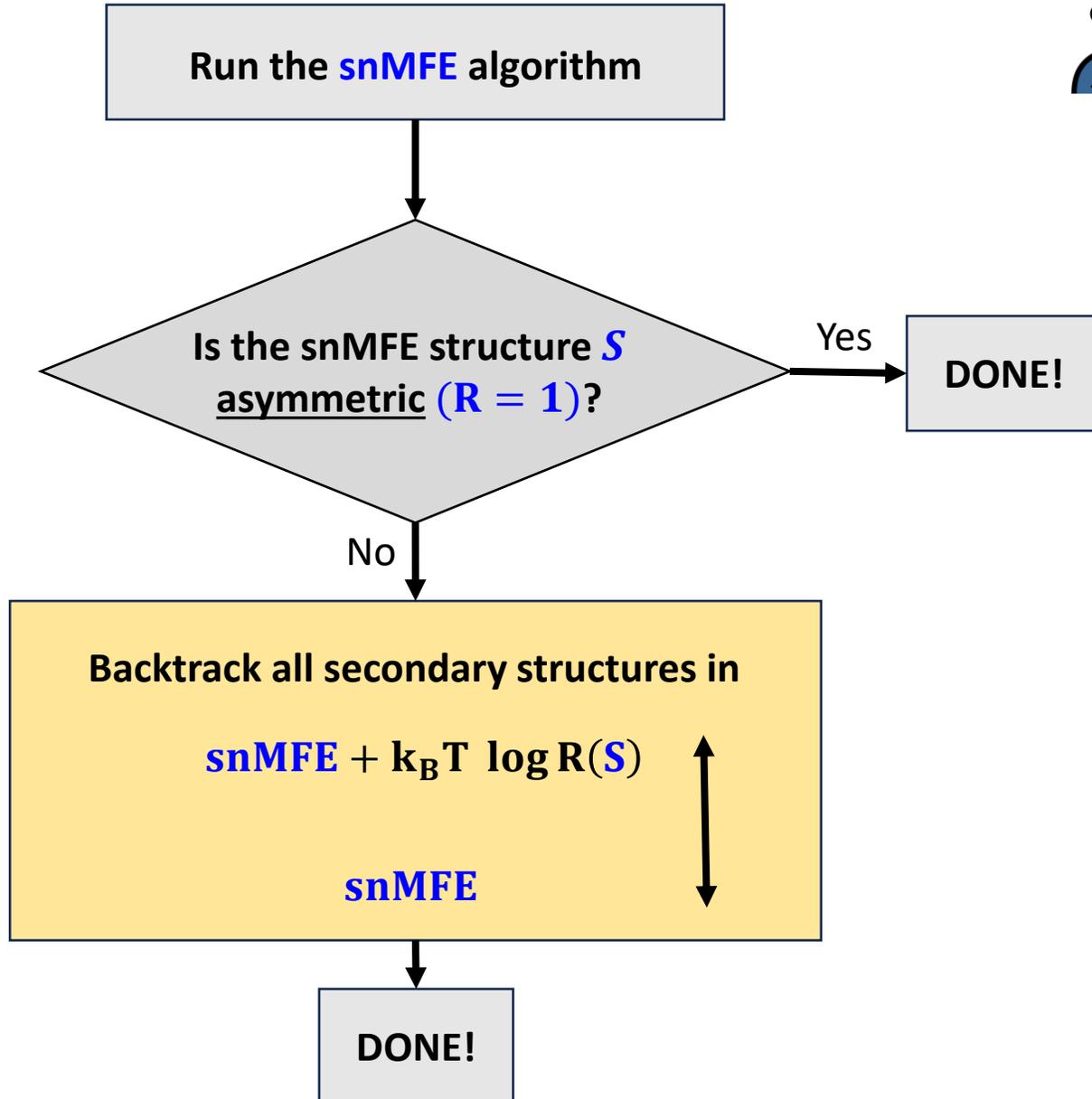
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Dirks et al. 2007 approach



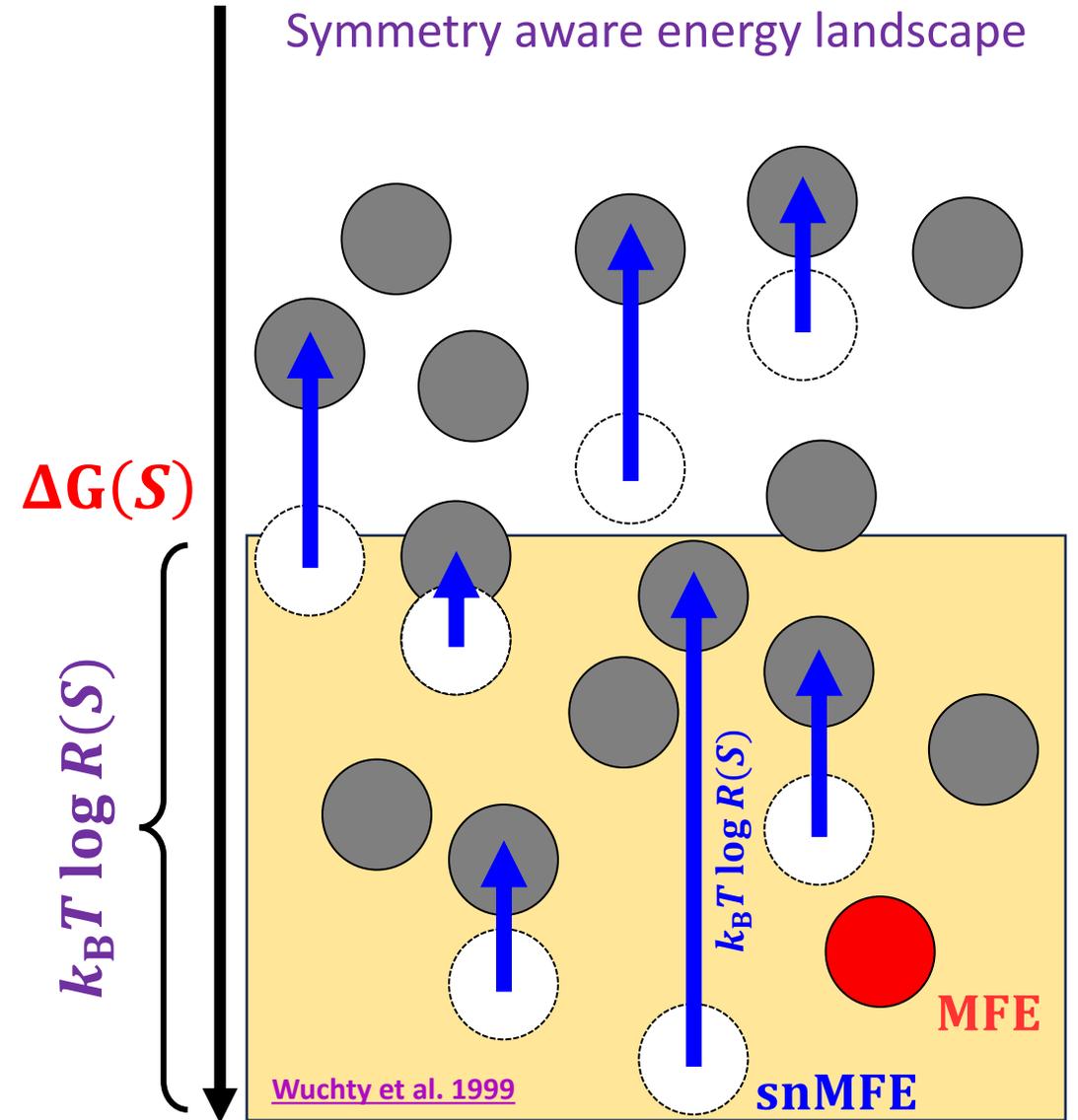
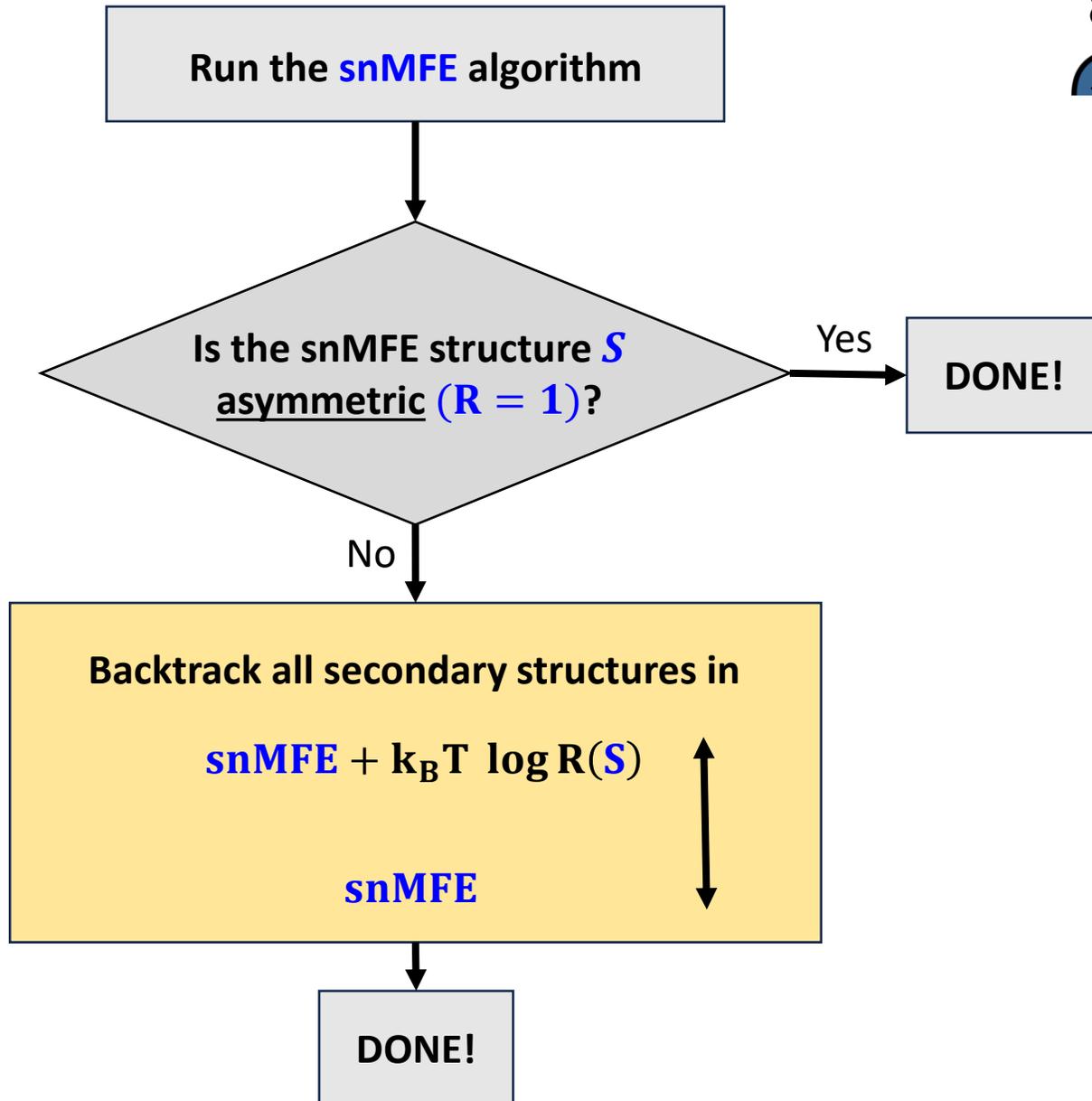
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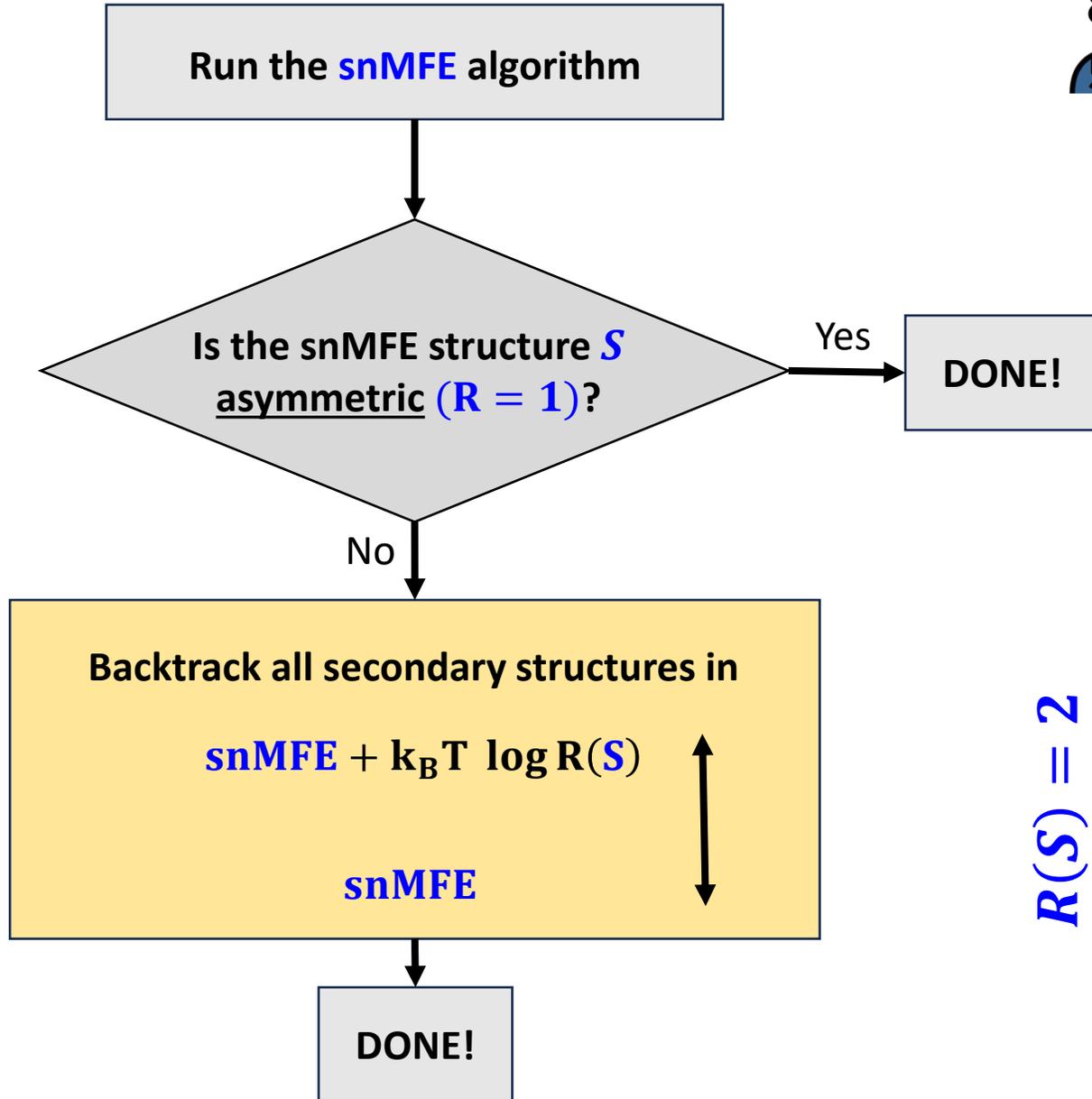
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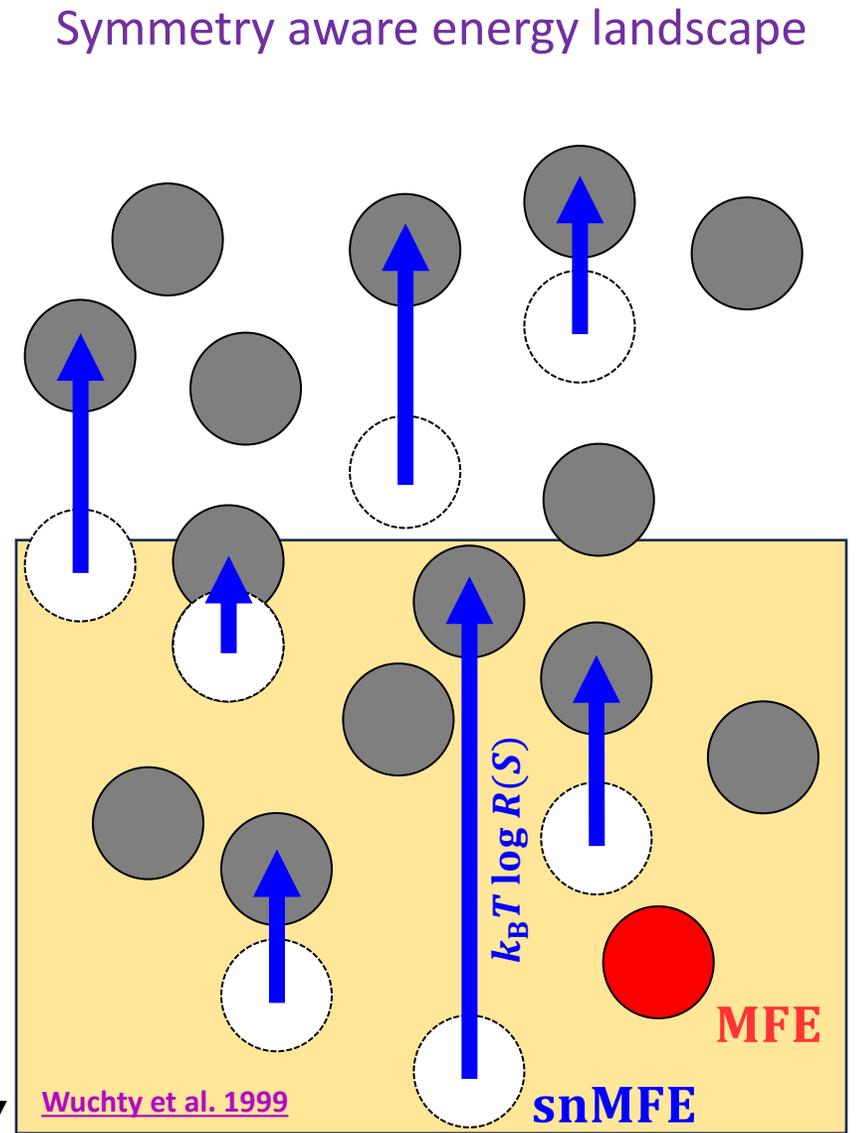


$$R(S) = 2$$

Exponential

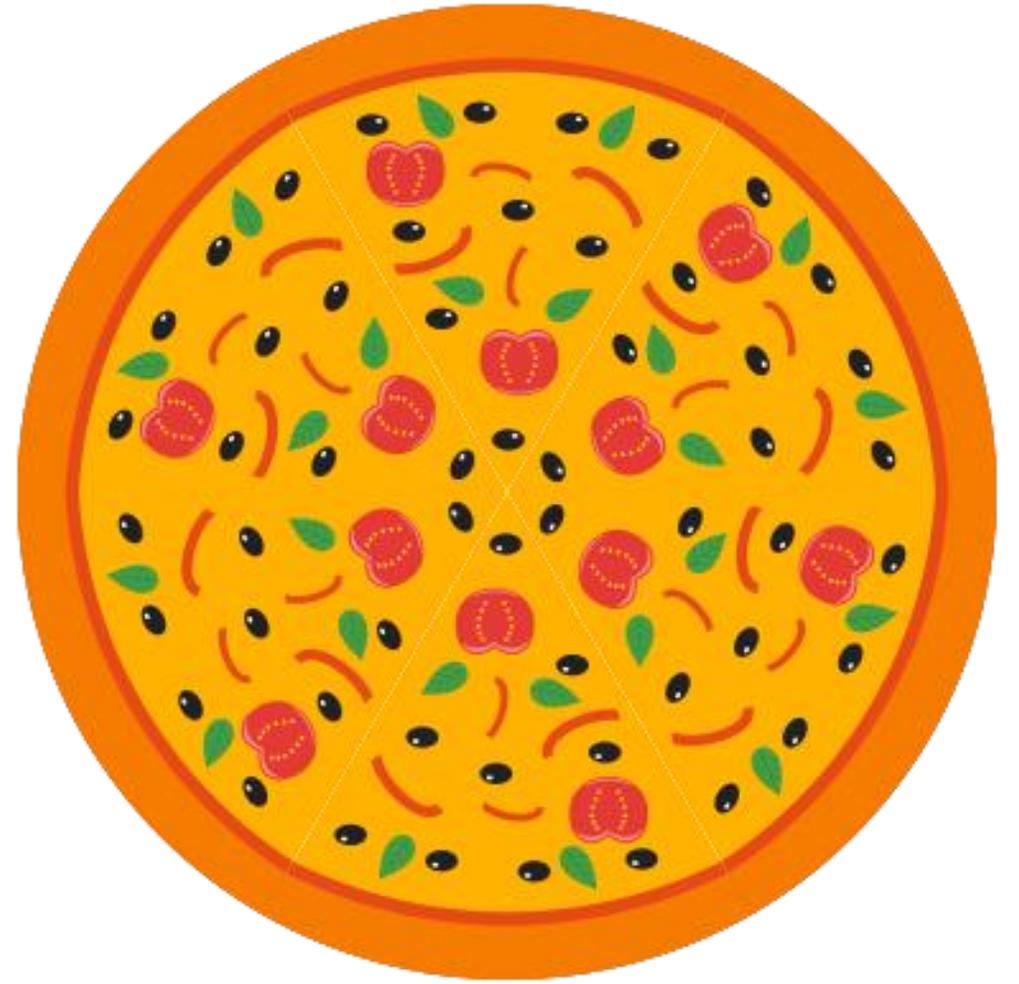
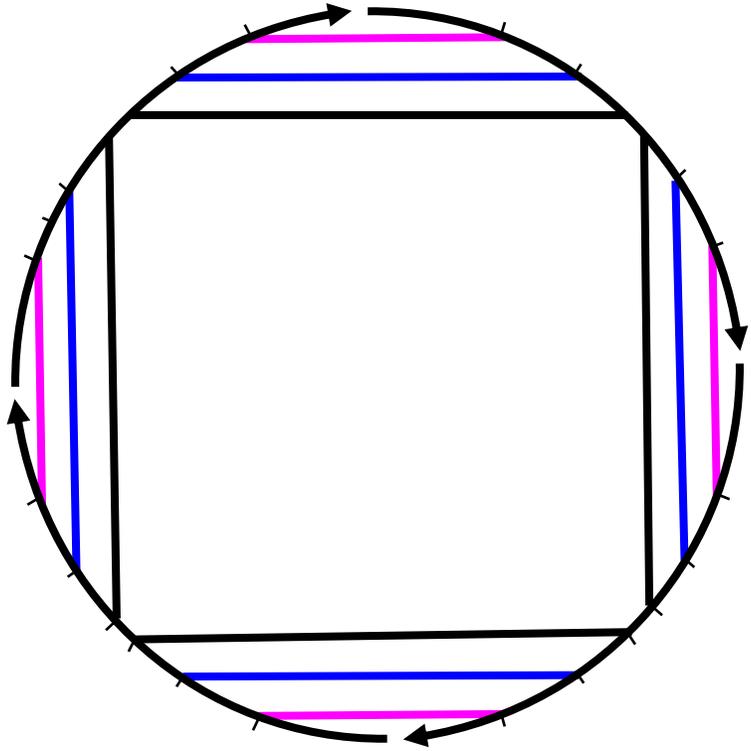
$$\Delta G(S)$$

$$k_B T \log R(S)$$



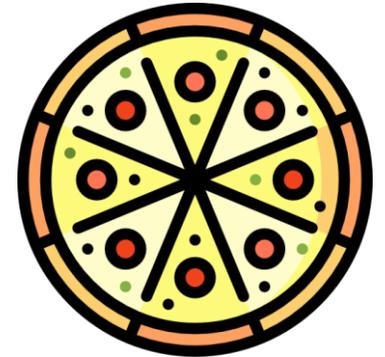
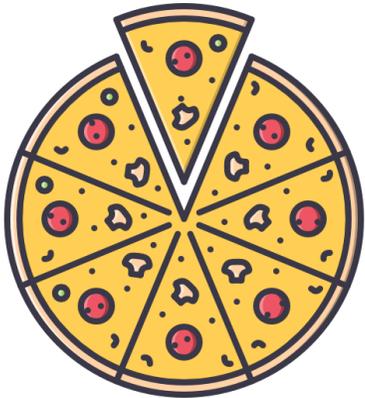
Our Approach

What if we could break symmetry with symmetry?



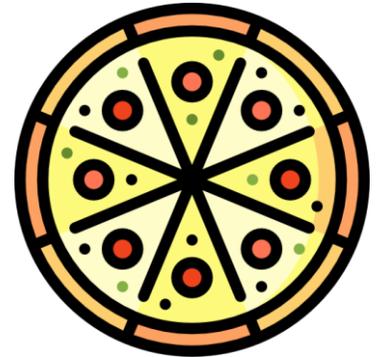
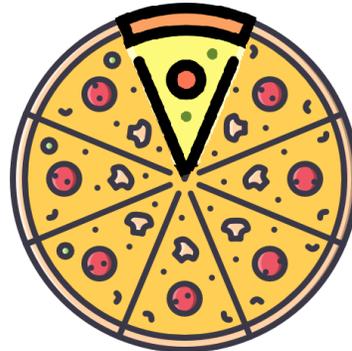
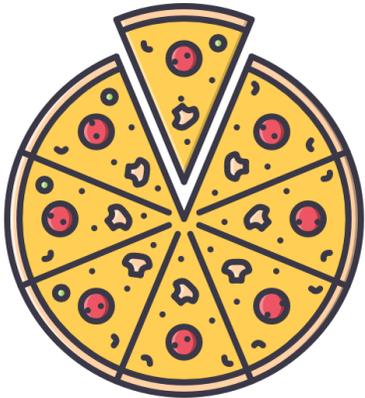
What if we could break **symmetry** with **symmetry**?

Slicing and swapping strategy



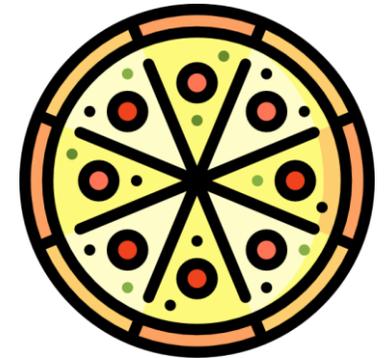
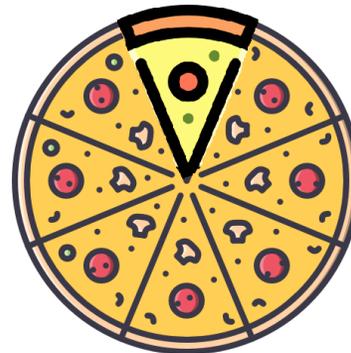
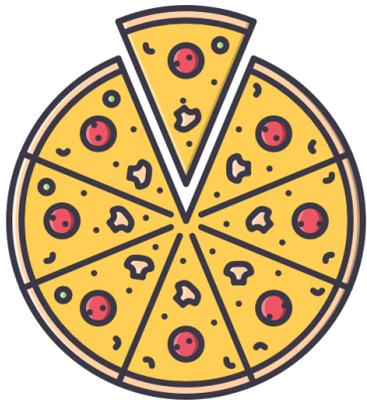
What if we could break **symmetry** with **symmetry**?

Slicing and swapping strategy



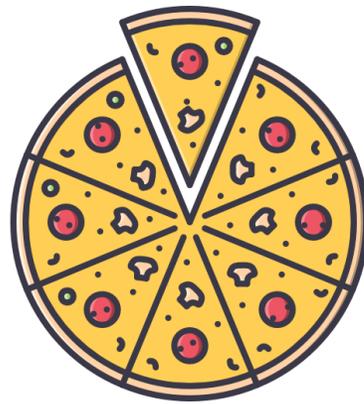
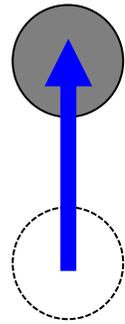
What if we could break **symmetry** with **symmetry**?

Slicing and swapping strategy



Sharing the same
Admissible pizza cut

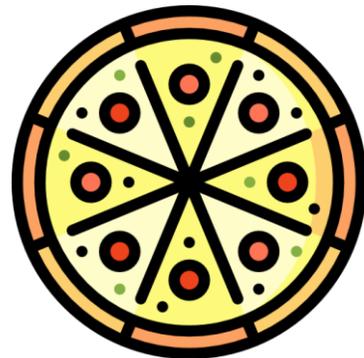
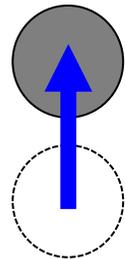
Unfavorable



S_x Symmetric

$\overline{\Delta G}(S)$

$$\overline{\Delta G}(S_y) \leq \overline{\Delta G}(S_x)$$

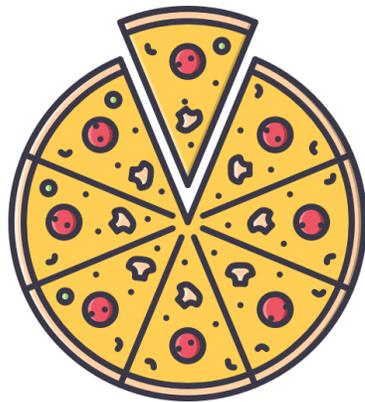
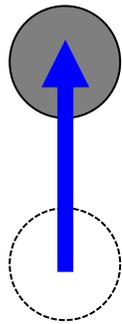


S_y Symmetric

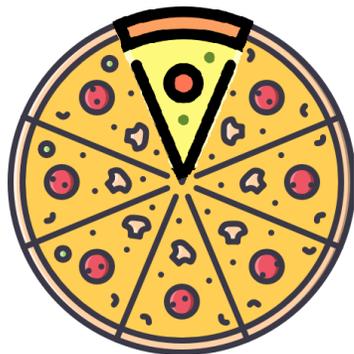
Favorable

S_x and S_y
Admissible pizza cut

Unfavorable

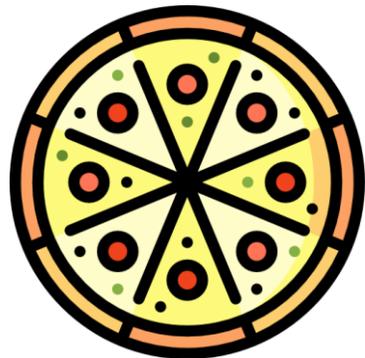
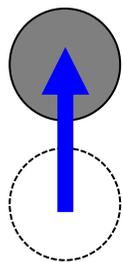


S_x Symmetric



S_z Asymmetric

S_x and S_y
Admissible pizza cut



S_y Symmetric

$\overline{\Delta G}(S)$

$$\overline{\Delta G}(S_y) \leq \overline{\Delta G}(S_x)$$

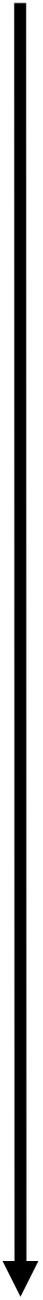
Favorable



Unfavorable

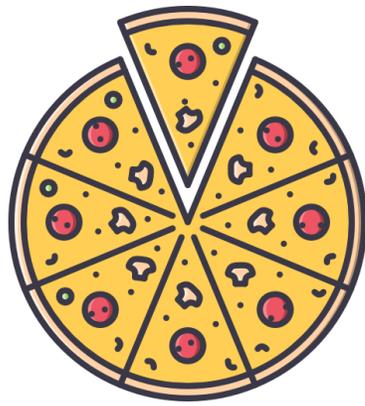
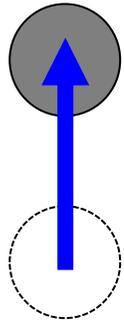
$\overline{\Delta G}(S)$

Favorable

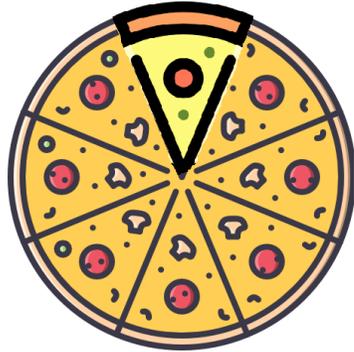


$$\overline{\Delta G}(S_y) \leq \overline{\Delta G}(S_x)$$

$$\overline{\Delta G}(S_y) \leq \overline{\Delta G}(S_z) = \Delta G(S_z) \leq \overline{\Delta G}(S_x)$$

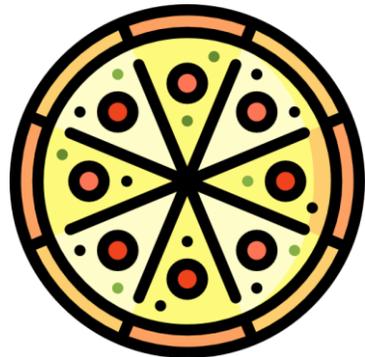
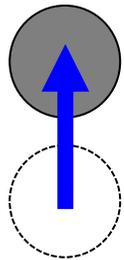


S_x Symmetric



S_z Asymmetric

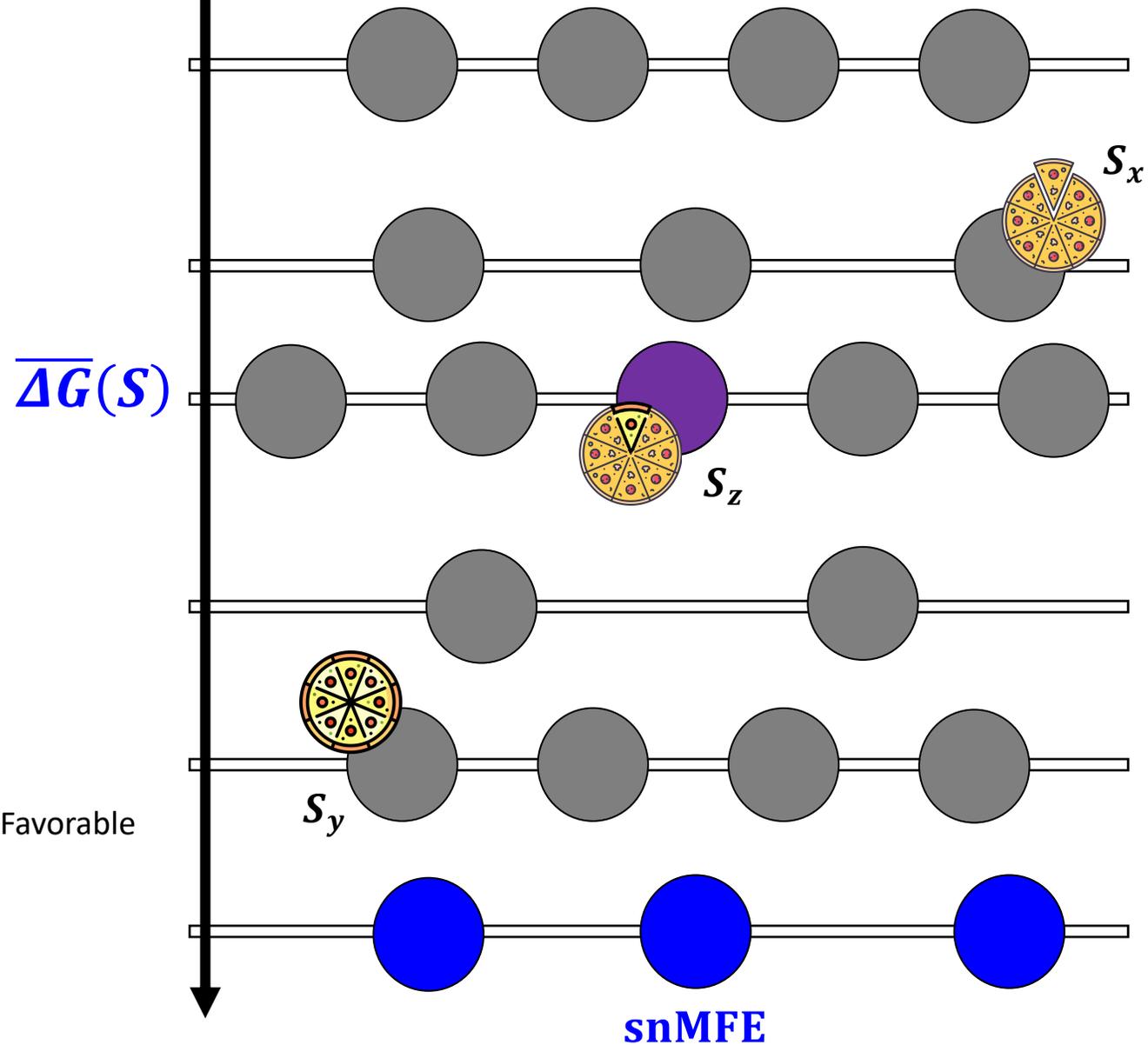
S_x and S_y
Admissible pizza cut



S_y Symmetric

Unfavorable

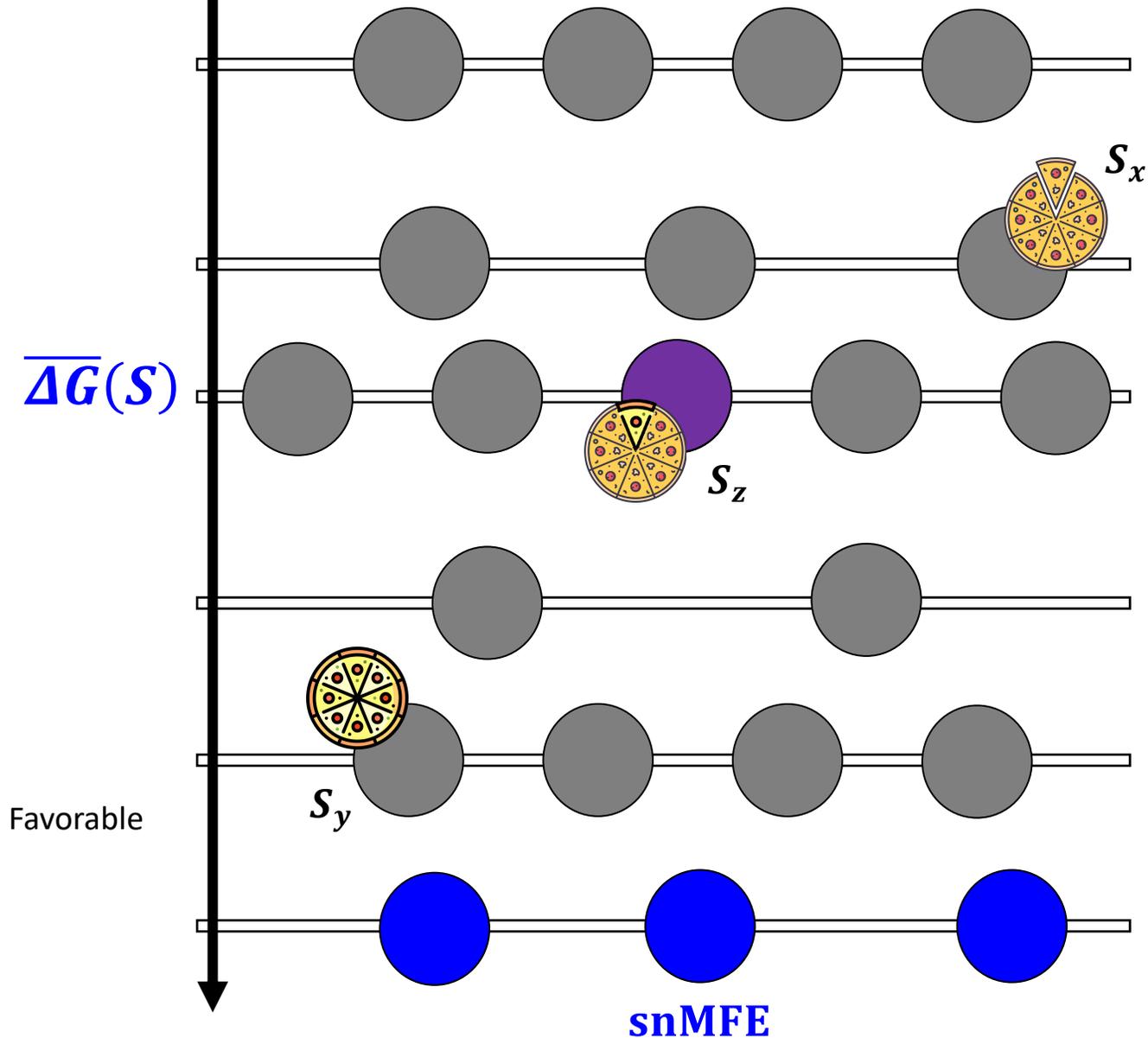
Symmetry naive energy landscape



S_x and S_y
Admissible pizza cut

Unfavorable

Symmetry naive energy landscape



S_x and S_y
Admissible pizza cut

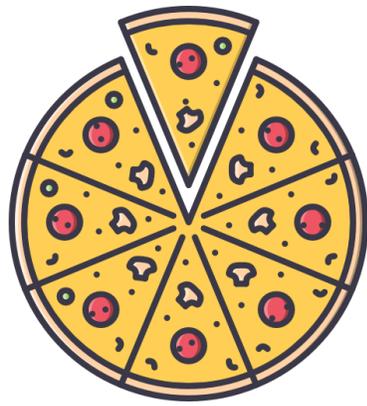
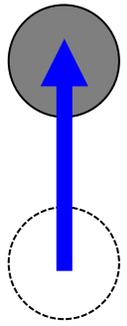
What is the maximum number of structures we need to backtrack until scanning S_x ?

Unfavorable

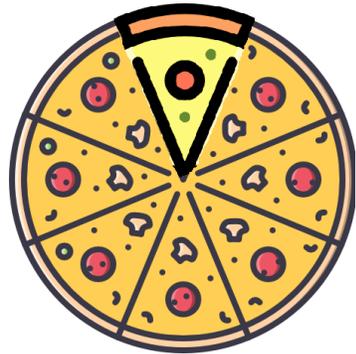
$\overline{\Delta G}(S)$

Favorable

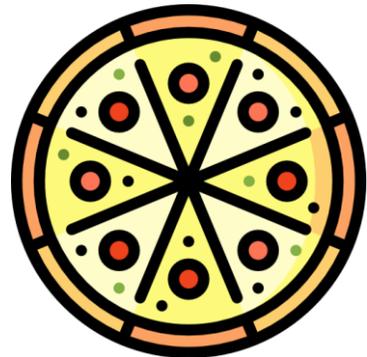
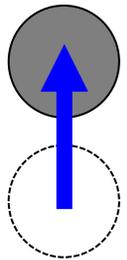
$$\overline{\Delta G}(S_y) \leq \overline{\Delta G}(S_z) = \Delta G(S_z) \leq \overline{\Delta G}(S_x)$$



S_x



S_z



S_y

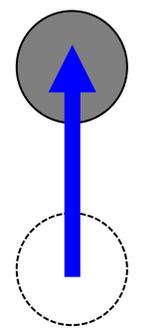
What is the maximum number of structures we need to backtrack until scanning S_x ?

Unfavorable

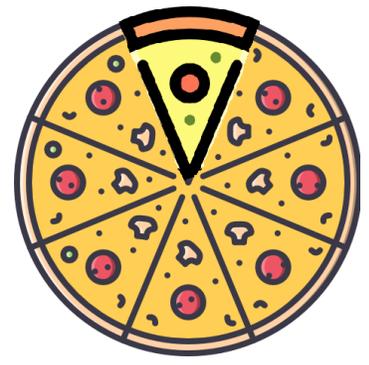
$\overline{\Delta G}(S)$

Favorable

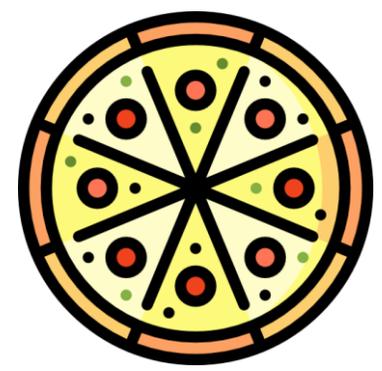
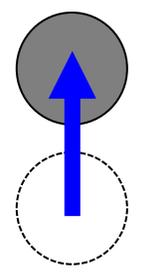
$$\overline{\Delta G}(S_y) \leq \overline{\Delta G}(S_z) = \Delta G(S_z) \leq \overline{\Delta G}(S_x)$$



S_x



S_z



S_y

What is the maximum number of structures we need to backtrack until scanning S_x ?

In worst case

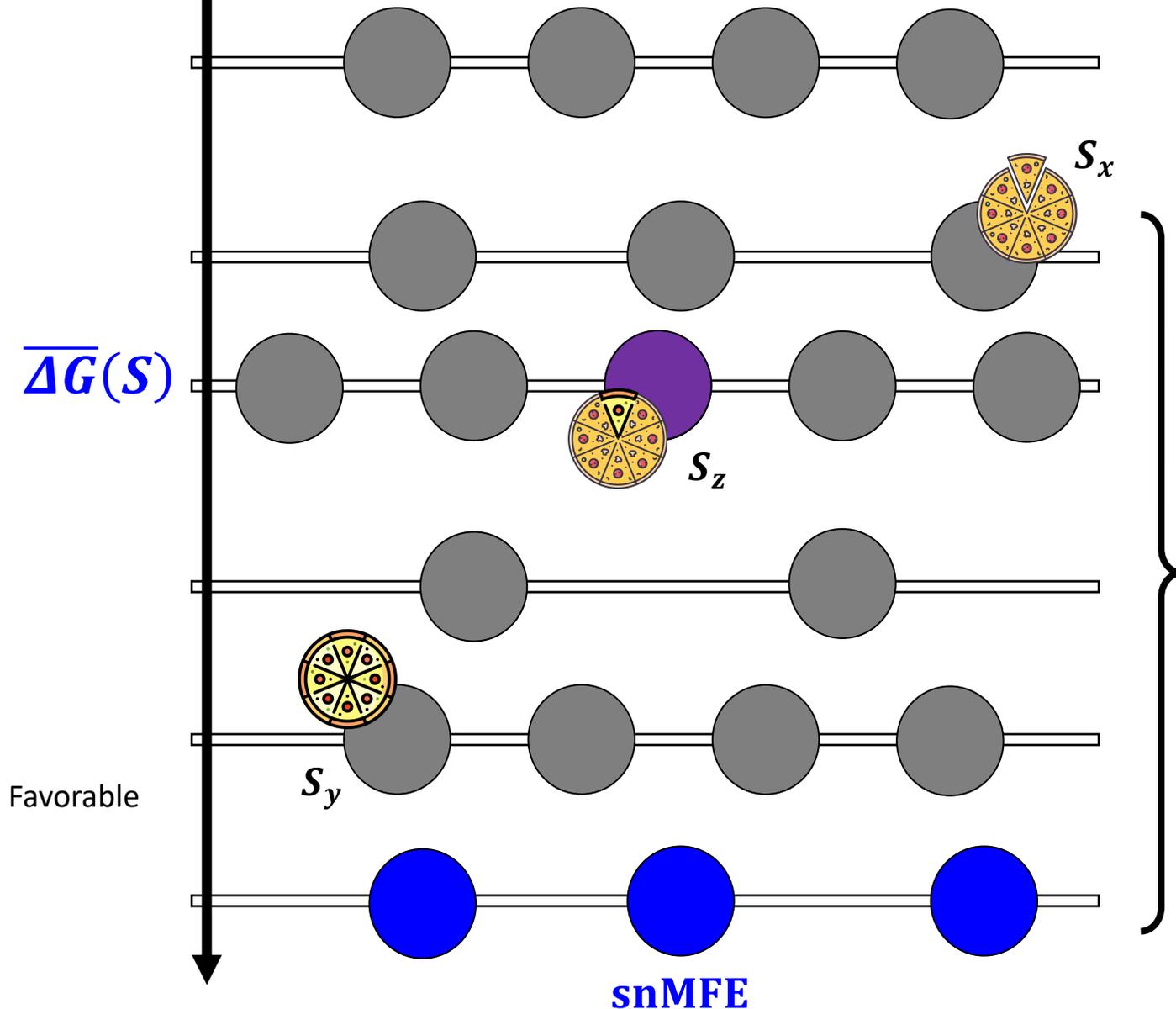
Upper bound \mathcal{U}

$$\frac{N-c}{v(\pi)} [\sigma(v(\pi)) - v(\pi)] + \frac{N^2}{16} = \mathcal{O}(N^2)$$

N : Number of bases
 c : Number of strands
 $v(\pi)$: Maximum degree of symmetry given the ordering π
 $\sigma(\cdot)$: Sum of divisors function

Unfavorable

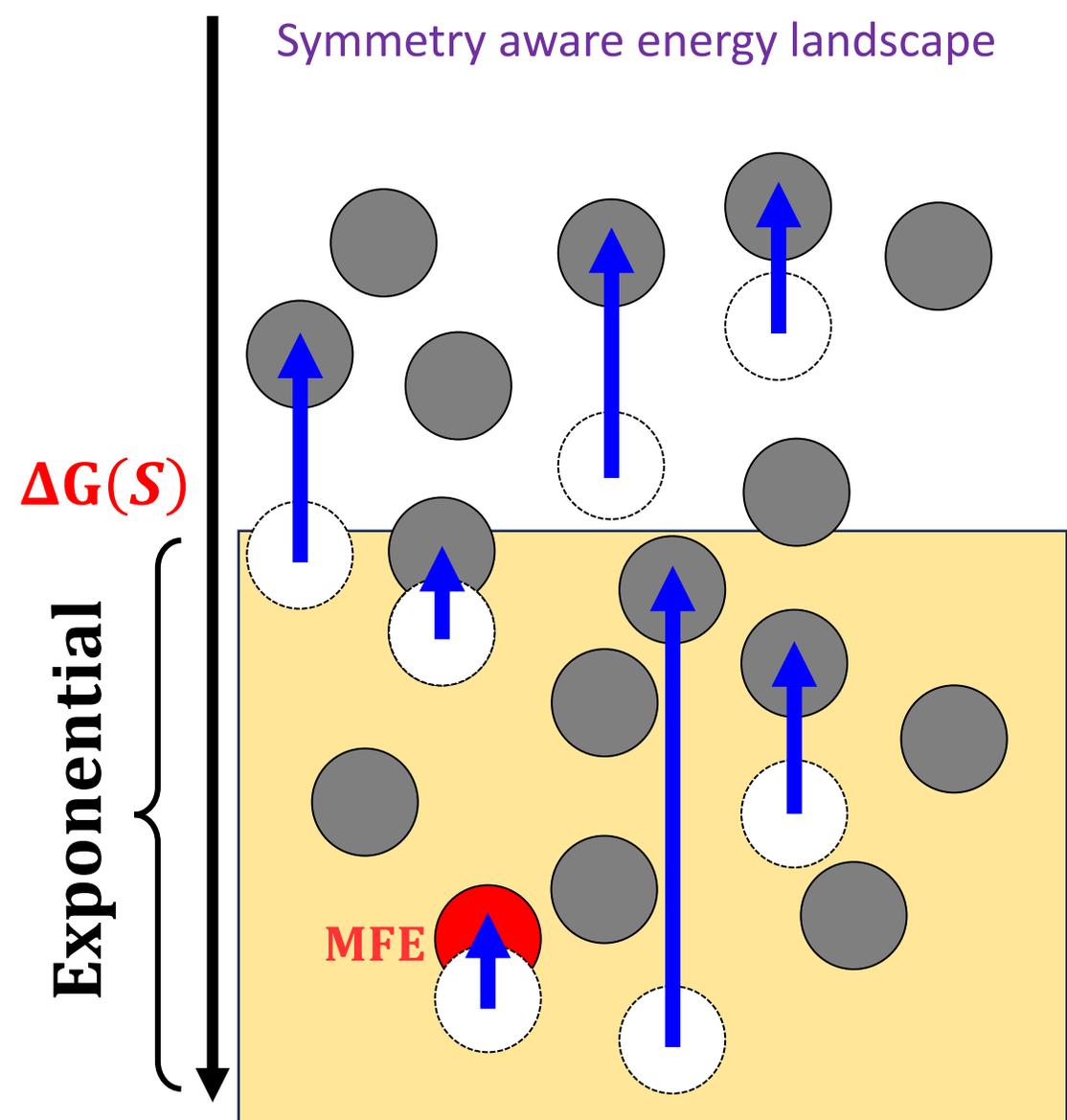
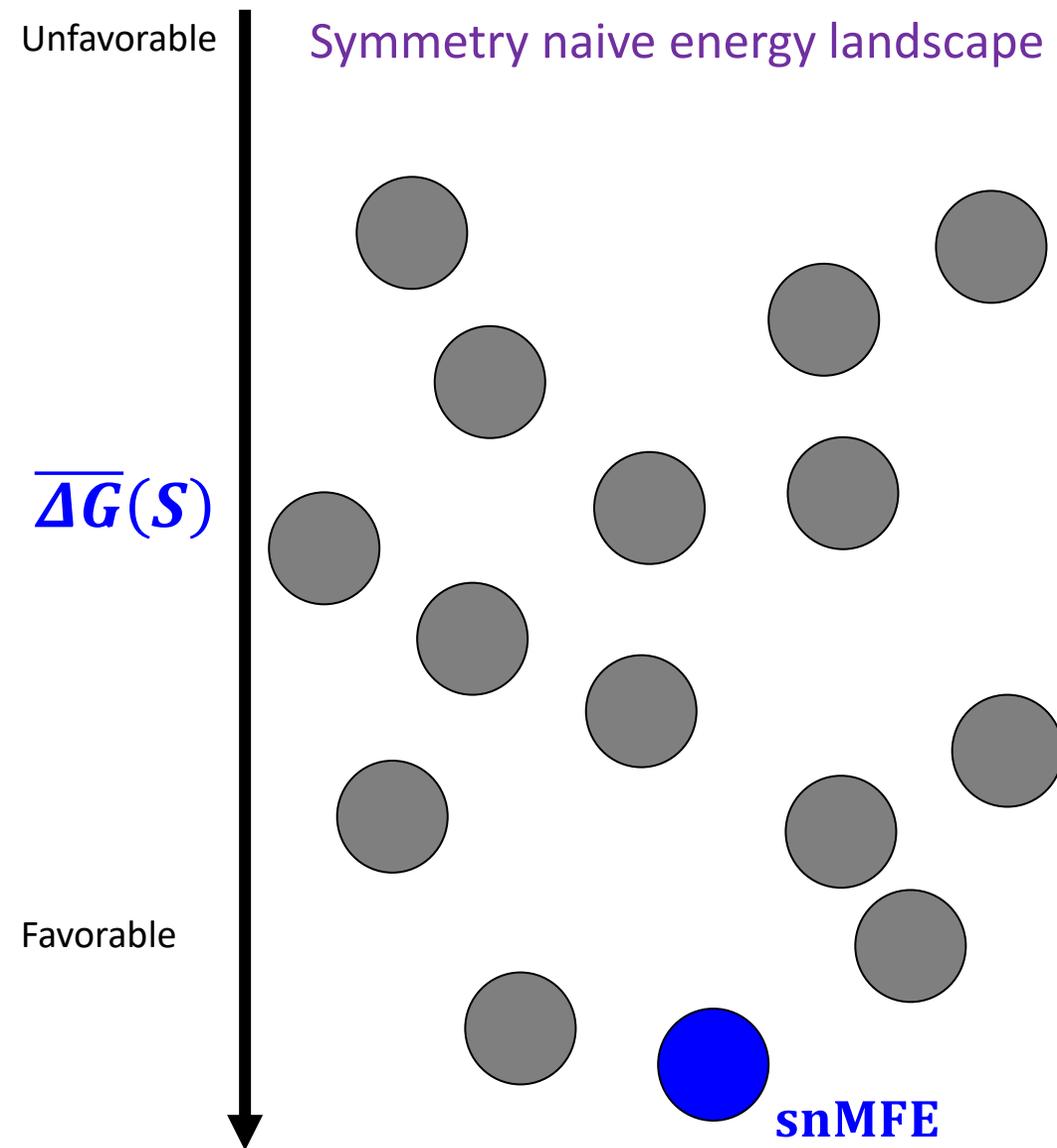
Symmetry naive energy landscape



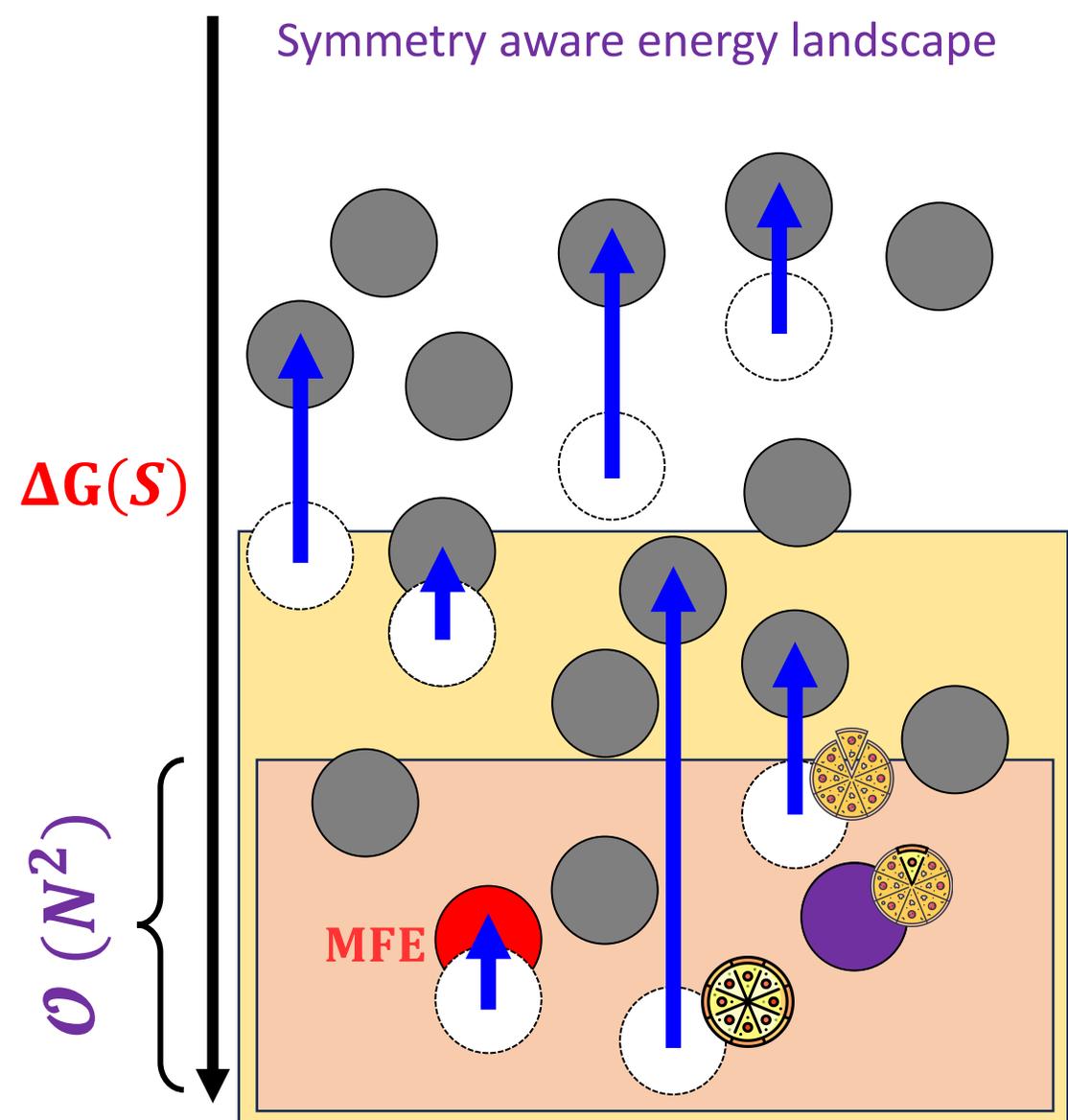
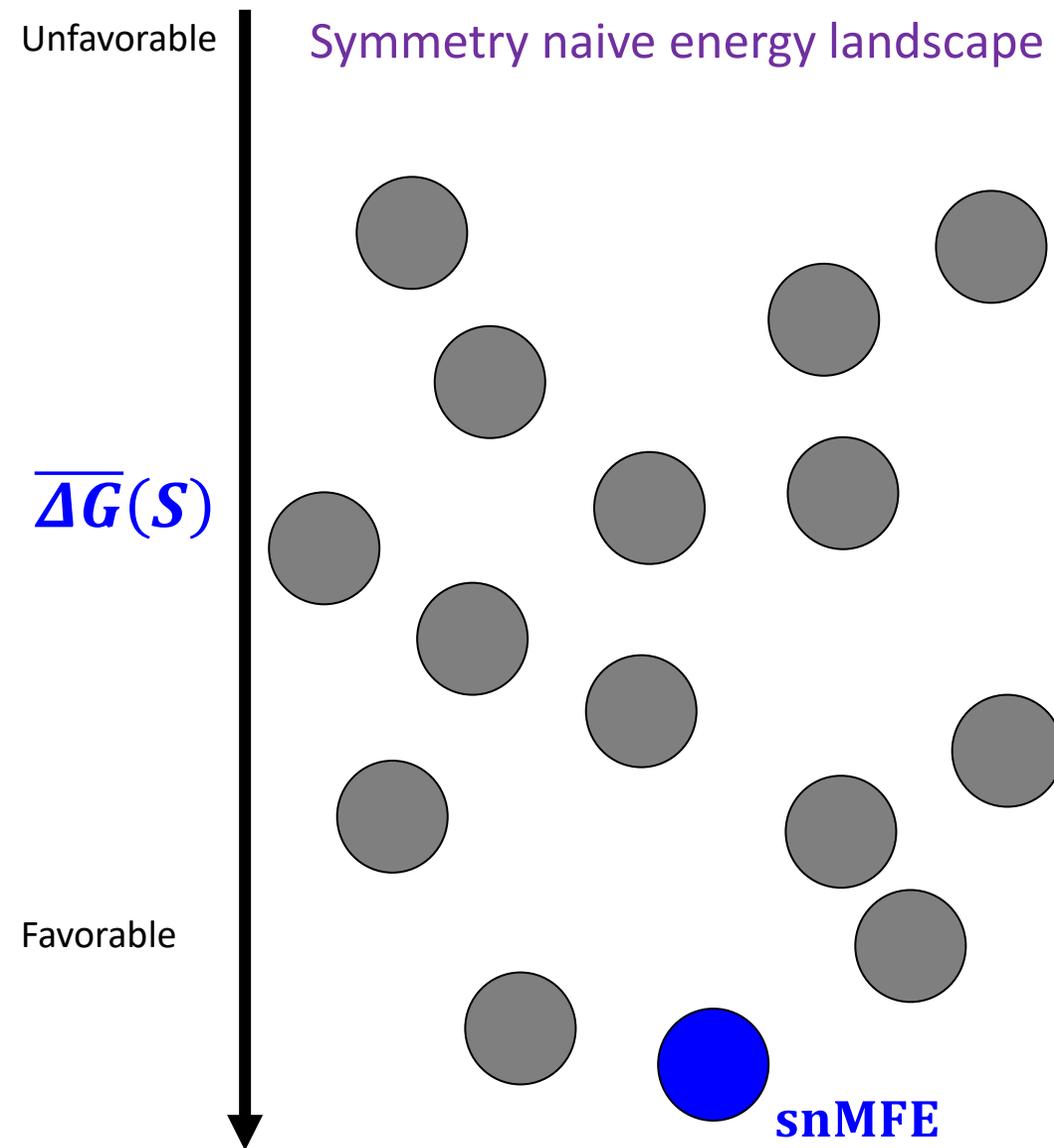
$$u = \mathcal{O}(N^2)$$

Favorable

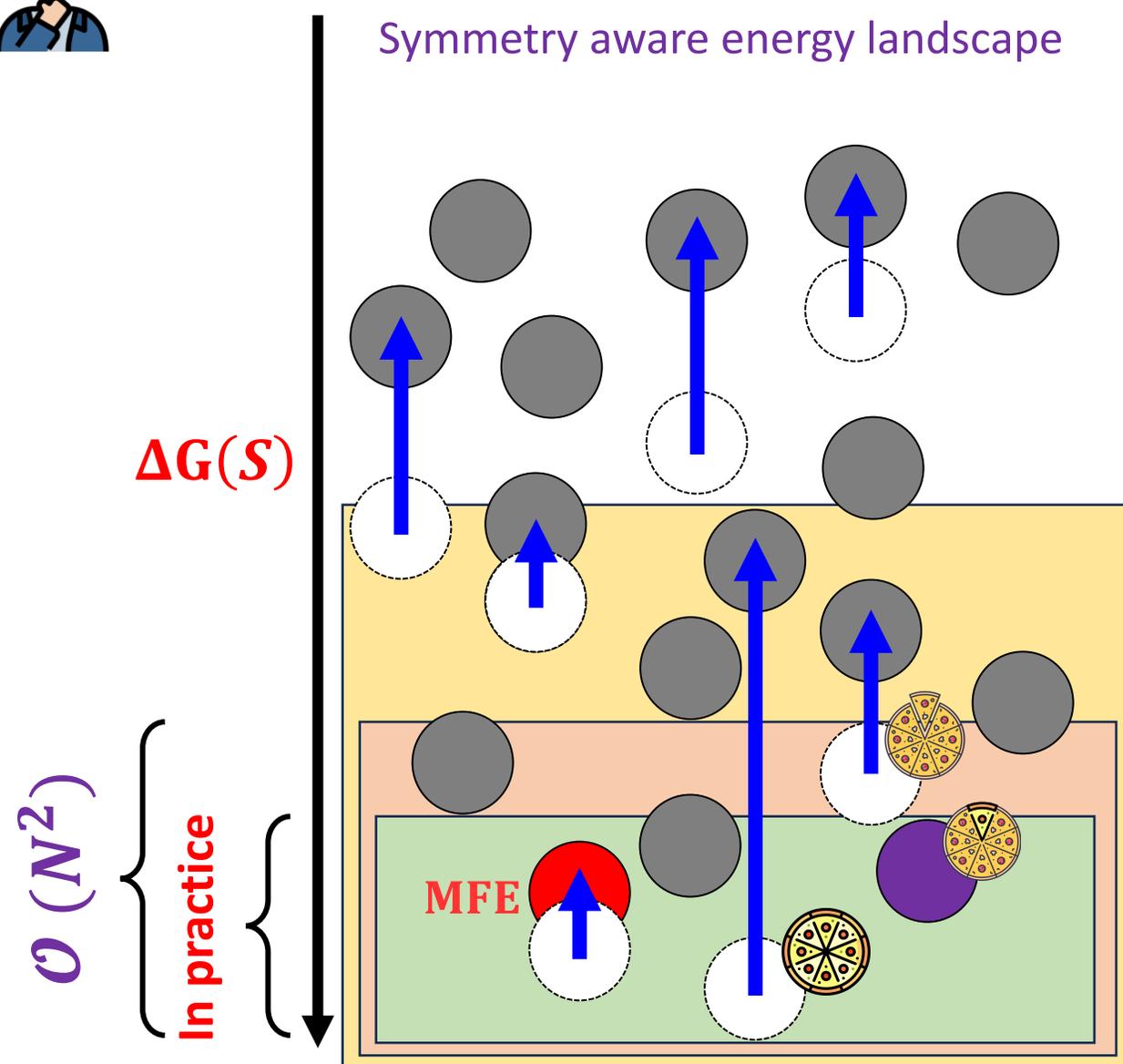
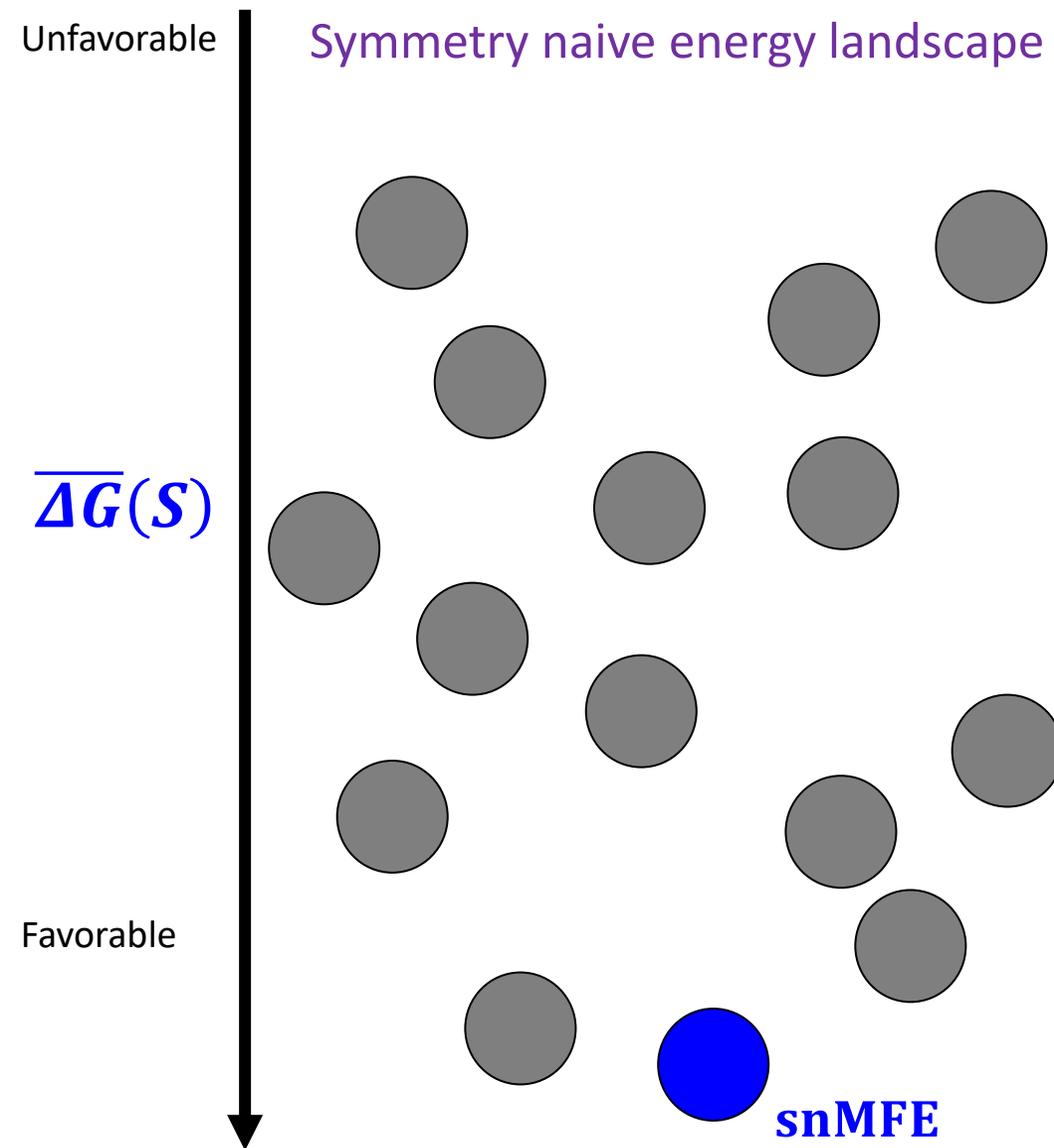
If **snMFE** structure is Symmetric ($R > 1$)



If snMFE structure is Symmetric ($R > 1$)



If **snMFE** structure is Symmetric ($R > 1$)



Computational complexity of MFE algorithms

Input Type	MFE
Single strand	$O(N^3)$
$c = O(1)$ <u>unique</u> strands	$O(N^3(c-1)!)$
$c = O(1)$ <u>allowing repeated</u> strands	$O(N^4(c-1)!)$
Multiple strands, unbounded, $O(N)$ strands	NP – Complete

N bases, c strands

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Thanks



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National University of Ireland Maynooth



Hamilton Institute



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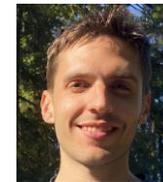
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Dave Doty



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